

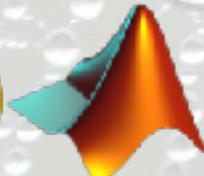
# Numerical Optimal Transport

<http://optimaltransport.github.io>

## *Gromov Wasserstein*

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**ENS**  
ÉCOLE NORMALE  
SUPÉRIEURE



# Overview

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- **Gromov Wasserstein**
- Entropic Regularization
- Applications
- GW Barycenters

# Gromov-Wasserstein

Inputs: {(similarity/kernel matrix, histogram)}

$$(d, \mu) \quad \mu = \sum_i \mu_i \delta_{x_i} \quad d_{i,i'} = d(x_i, x_{i'})$$

$$(\bar{d}, \nu) \quad \nu = \sum_j \nu_j \delta_{y_j} \quad \bar{d}_{j,j'} = \bar{d}(y_j, y_{j'})$$

**Def.** Gromov-Wasserstein distance:

$$\text{GW}_p^p(d, \mu, \bar{d}, \nu) \stackrel{\text{def.}}{=} \min_{T \in C_{\mu, \nu}} \mathcal{E}_{d, \bar{d}}^p(T)$$

$$\mathcal{E}_{d, \bar{d}}^p(T) \stackrel{\text{def.}}{=} \sum_{i, i', j, j'} |d_{i, i'} - \bar{d}_{j, j'}|^p T_{i, j} T_{i', j'}$$

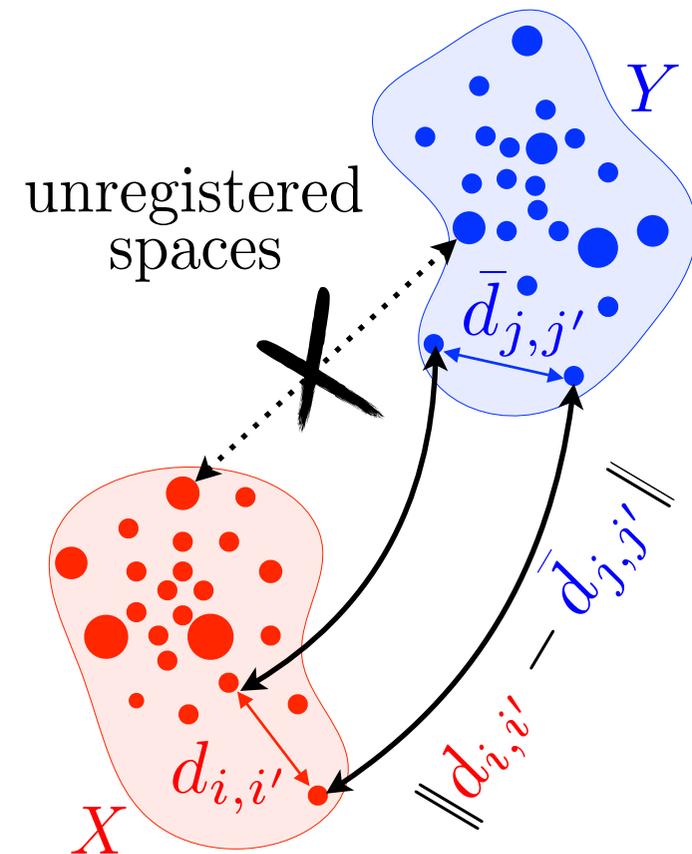
[Memoli 2011]

[Sturm 2012]

Computation of GW is a QAP:

→ NP-hard in general.

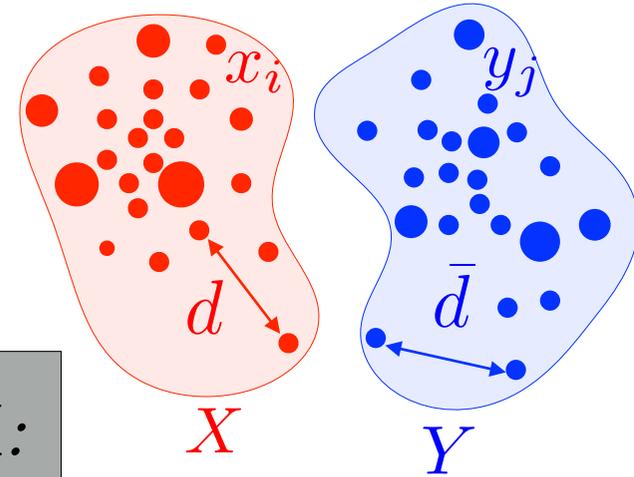
→ need for a fast approximate solver.



# Gromov-Wasserstein as a Metric

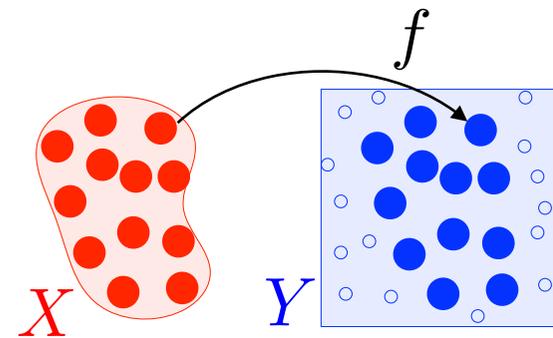
$$\mu = \sum_i \mu_i \delta_{x_i} \in \mathcal{M}_+^1(X) \quad d_{i,i'} = d(x_i, x_{i'})$$

$$\nu = \sum_j \nu_j \delta_{y_j} \in \mathcal{M}_+^1(Y) \quad \bar{d}_{j,j'} = \bar{d}(y_j, y_{j'})$$



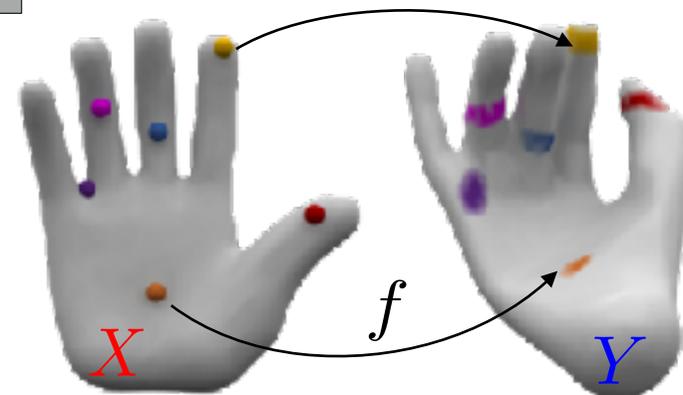
**Def.** Metric-measured spaces  $(X, \mu, d) \in \mathbb{M}$ :  
 $\mu \in \mathcal{M}_+^1(X)$  and  $d$  is a distance on  $X$

**Def.** Isometries on  $\mathbb{M}$ :  $(\mu, d) \sim (\nu, \bar{d})$   
 $\iff \exists f : X \rightarrow Y, \begin{cases} f_{\#}\mu = \nu, \\ d(x, x') = \bar{d}(f(x), f(x')). \end{cases}$



**Prop.** GW defines a distance on  $\mathbb{M}/\sim$ .  
 [Memoli 2011]

$\longrightarrow$  “bending-invariant” objects recognition.



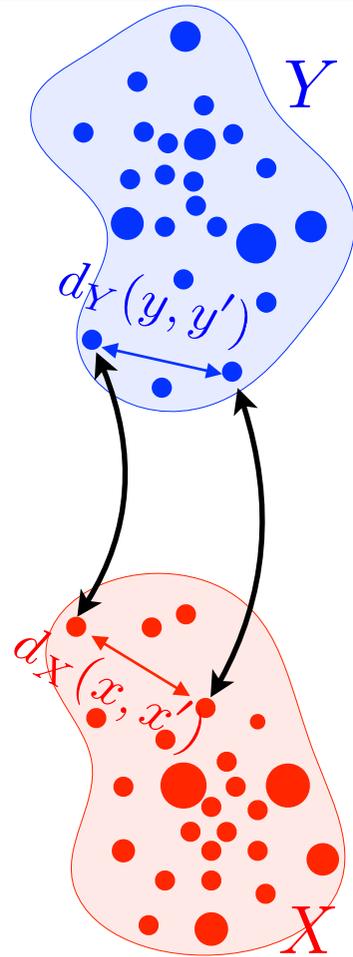
# For Arbitrary Spaces

Metric-measure spaces  $(X, Y)$ :  $(d_X, \mu), (d_Y, \nu)$

**Def.** Gromov-Wasserstein distance:

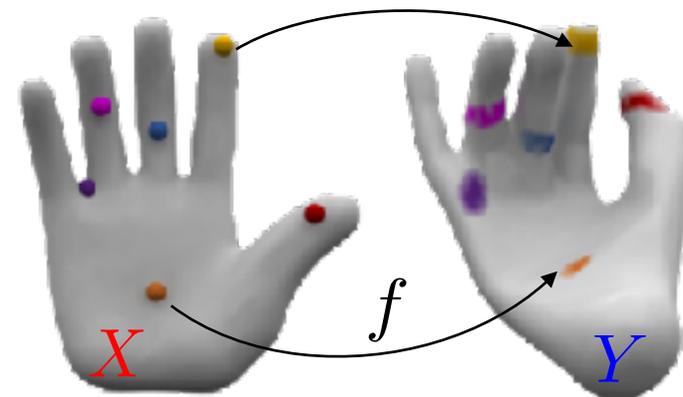
$$\text{GW}_2^2(d_X, \mu, d_Y, \nu) \stackrel{\text{def.}}{=} \min_{\pi \in \Pi(\mu, \nu)} \int_{X^2 \times Y^2} |d_X(x, x') - d_Y(y, y')|^2 d\pi(x, y) d\pi(x', y')$$

[Sturm 2012] [Memoli 2011]



**Prop.** GW is a distance on mm-spaces/isometries.

- “bending-invariant” objects recognition.
- QAP: NP-hard in general.
- need for a fast approximate solver.



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# Entropic Gromov Wasserstein

**Def.** *Entropic Gromov-Wasserstein*

$$\text{GW}_{p,\varepsilon}^p(d, \mu, \bar{d}, \nu) \stackrel{\text{def.}}{=} \min_{T \in \mathcal{C}_{\mu,\nu}} \mathcal{E}_{d,\bar{d}}^p(T) - \varepsilon H(T)$$

**Def.** *Projected mirror descent:*

$$T \leftarrow \text{Proj}_{\mathcal{C}_{\mu,\nu}}^{\text{KL}} \left( T \odot e^{-\tau(-\nabla \mathcal{E}_{d,\bar{d}}^p(T) - \varepsilon \nabla H(T))} \right)$$

where  $\text{Proj}_{\mathcal{C}_{\mu,\nu}}^{\text{KL}}(K) \stackrel{\text{def.}}{=} \text{argmin}_T \{ \text{KL}(T|K) ; T \in \mathcal{C}_{\mu,\nu} \}$

**Prop.** for  $\tau = 1/\varepsilon$ , the iteration reads

$$T \leftarrow \text{Sinkhorn}(\mu, \nu, -d \times T \times \bar{d})$$

**Prop.**  $T$  converges to a stationary point.

func  $T = \text{GW}(C, \bar{C}, p, q)$

**initialization:**

$$T \leftarrow \mu \nu^\top$$

**repeat:**

$$D \leftarrow -d \times T \times \bar{d}$$

$$T \leftarrow \text{Sinkhorn}(\mu, \nu, D)$$

**until convergence.**

**return**  $T$

# Overview

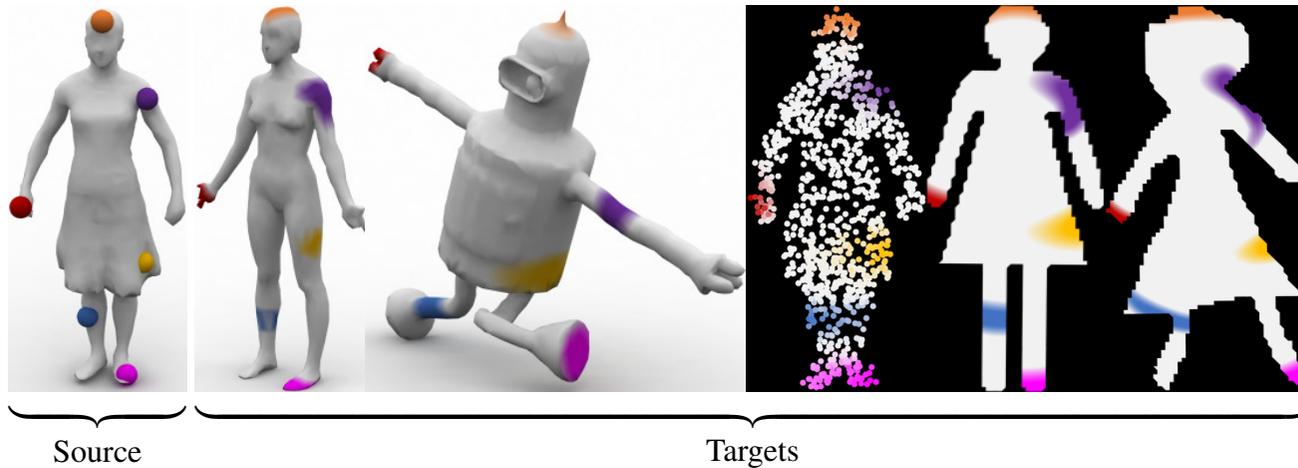
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# Applications of GW: Shapes Analysis

Use  $T$  to define registration between:

Shape ↔ Shape



Colors distribution ↔ Shape

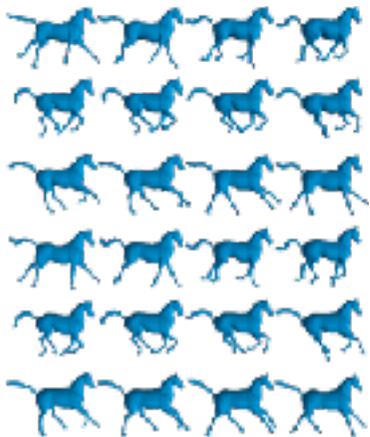


Shapes  
 $(X_s)_s$

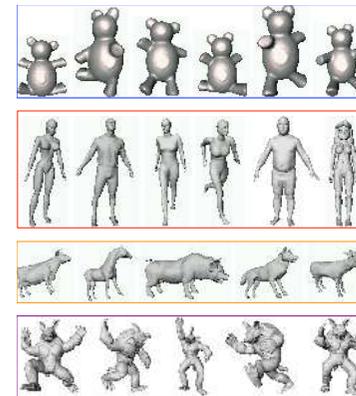
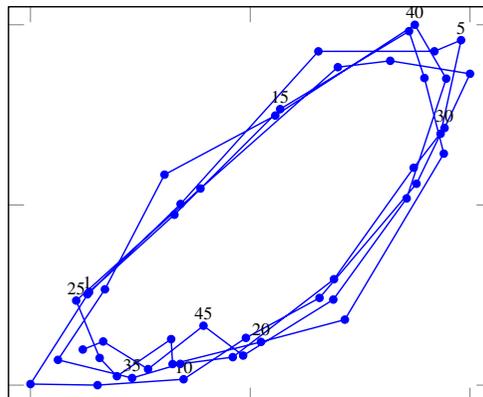
Geodesic distances  
 $d_s = (D_{X_s}(x_i, x_{i'}))_{i,i'}$

GW distances  
 $(GW_\epsilon(d_s, d_{s'}))_{s,s'}$

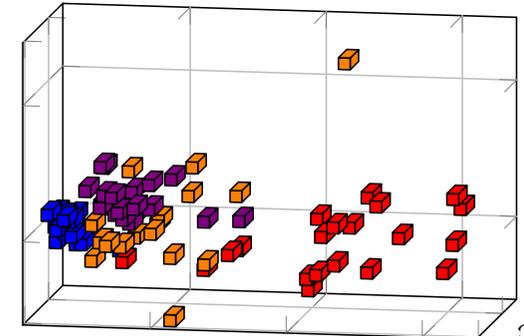
MDS  
Vizualization



MDS in 2-D



MDS in 3-D



# Applications of GW: Quantum Chemistry

*Input:* Molecules with positions and charges  $\mu = \sum_i \mu_i \delta_{x_i}$ .

*Regression problem:* approximate ground state energy  $\mu \mapsto f(\mu)$ .

$\rightarrow f$  by solving DFT approximation is too costly.

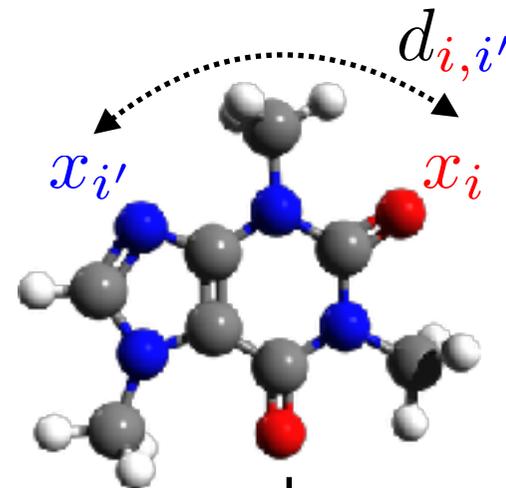
*Coulomb matrices*  $d = d(\mu)$ :

$$d_{i,i'} \stackrel{\text{def.}}{=} \begin{cases} \frac{\mu_i \mu_{i'}}{\|x_i - x_{i'}\|} & \text{for } (i \neq i') \\ \frac{1}{2} \mu_i^{2.4} & \text{for } (i = i'). \end{cases}$$

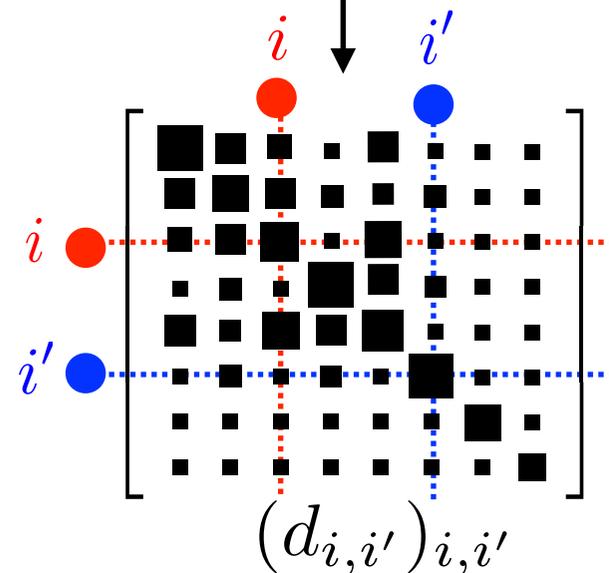
*Learning:*  $(\mu_s, f(\mu_s))_s \rightarrow$  approximation  $\tilde{f}$ .

*GW-interpolation:*  $\tilde{f}(\mu) = f(\mu_{s^*})$

$$s^* = \operatorname{argmin}_s \operatorname{GW}(d(\mu), d(\mu_s))$$



[Rupp et al 2012]



Algorithm	$\ f - \tilde{f}\ _1$
$k$ -nearest neighbors	71.54
Linear regression	20.72
Gaussian kernel ridge regression	8.57
Laplacian kernel ridge regression (8)	3.07
Multilayer Neural Network (1000)	3.51
<b>GW 3-nearest neighbors</b>	<b>10.83</b>

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# Gromov-Wasserstein Geodesics

**Def.** *Gromov-Wasserstein Geodesic*

$$(\mu_t, d_t) \in \underset{(\mu, d) \in \mathbb{X}}{\operatorname{argmin}} (1-t) \operatorname{GW}_2^2(\mu_0, d_0, \mu, d) + t \operatorname{GW}_2^2(\mu_1, d_1, \mu, d)$$

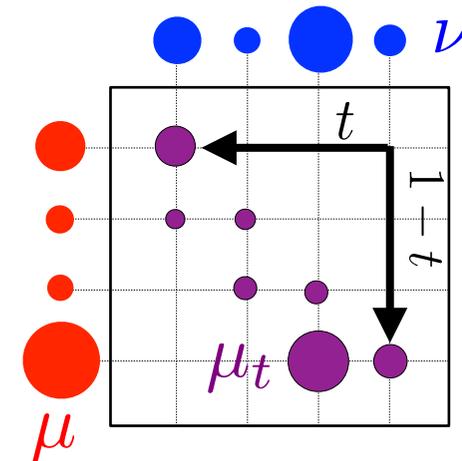
Optimal coupling  $T^*$ :  $\operatorname{GW}_2^2(d_0, \mu_0, d_1, \mu_1) \stackrel{\text{def.}}{=} \mathcal{E}_{d_0, d_1}^2(T^*)$

**Prop.** One can define  $(\mu_t, d_t)$  on  $X \times Y$  as

$$\mu_t = \sum_{i,j} T_{i,j}^* \delta_{x_i, y_j}$$

$$d_t((x, y), (x', y')) = (1-t) d_0(x, x') + t d_1(y, y')$$

[Sturm 2012]



→  $X \times Y$  is not practical for most applications.

(need to fix the size of the geodesic embedding space)

→ Extension to more than 2 input spaces?

# Gromov-Wasserstein Barycenters

*Input:* | Measures  $(\mu_s)_s$ , matrices  $(d_s)_s$   
 | Weights  $\lambda$ , size  $N$ ,  $\mu \in \mathbb{R}_+^N$  probability vector

**Def. GW Barycenters**

$$\min_{d \in \mathbb{R}^{N \times N}} \sum_s \lambda_s \text{GW}_{2,\varepsilon}^2(d_s, \mu_s, d, \mu)$$

$$\min_{d, (T_s)_s} \left\{ \sum_s \lambda_s (\mathcal{E}_{d,d_s}^2(T_s) - \varepsilon H(T_s)) ; \forall s, T_s \in \mathcal{C}_{\mu, \mu_s} \right\}$$

Alternating minimization:

func  $C = \text{GW-bary}(d_s, \mu_s, \mu)_s$

initialization:  $C \leftarrow C_0$

repeat:

for  $s = 1$  to  $S$  do

On  $T_s \rightarrow T_s \leftarrow \text{GW}(d, \mu, d_s, \mu_s)$

On  $d \rightarrow d \leftarrow \frac{1}{\mu \mu^\top} \sum \lambda_s T_s^\top d_s T_s$

until convergence.

return  $C$

