

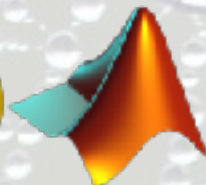
Numerical Optimal Transport

<http://optimaltransport.github.io>

Gromov Wasserstein

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ENS
ÉCOLE NORMALE
SUPÉRIEURE



Overview

- **Gromov Wasserstein**
- Entropic Regularization
- Applications
- GW Barycenters

Gromov-Wasserstein

Inputs: {(similarity/kernel matrix, histogram)}

$$(d, \mu) \quad \mu = \sum_i \mu_i \delta_{x_i} \quad d_{i,i'} = d(x_i, x_{i'})$$

$$(\bar{d}, \nu) \quad \nu = \sum_j \nu_j \delta_{y_j} \quad \bar{d}_{j,j'} = \bar{d}(y_j, y_{j'})$$

Def. Gromov-Wasserstein distance:

$$GW_p^p(d, \mu, \bar{d}, \nu) \stackrel{\text{def.}}{=} \min_{T \in C_{\mu, \nu}} \mathcal{E}_{d, \bar{d}}^p(T)$$

$$\mathcal{E}_{d, \bar{d}}^p(T) \stackrel{\text{def.}}{=} \sum_{i, i', j, j'} |d_{i, i'} - \bar{d}_{j, j'}|^p T_{i, j} T_{i', j'}$$

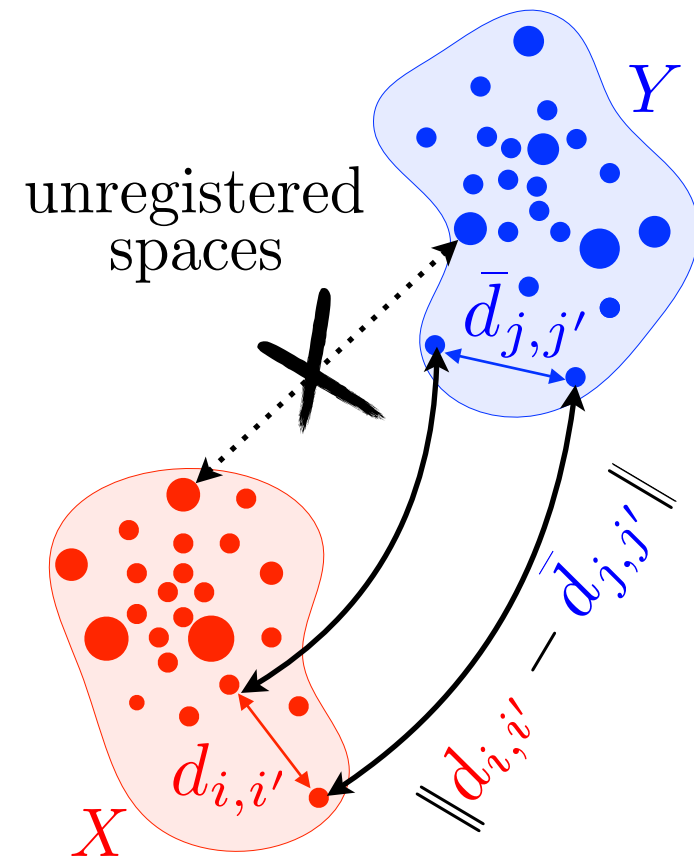
[Memoli 2011]

[Sturm 2012]

Computation of GW is a QAP:

→ NP-hard in general.

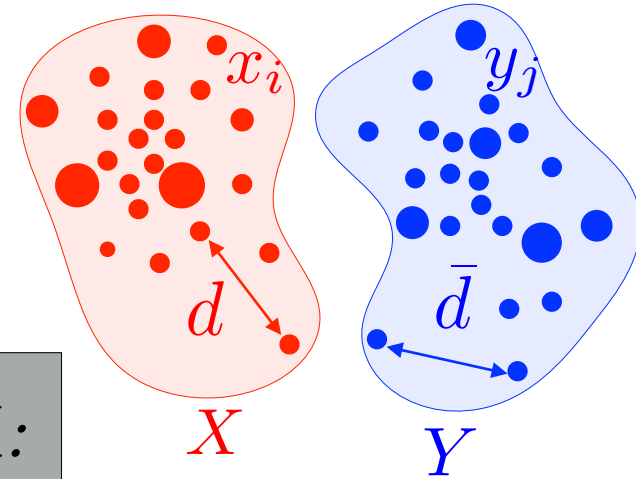
→ need for a fast approximate solver.



Gromov-Wasserstein as a Metric

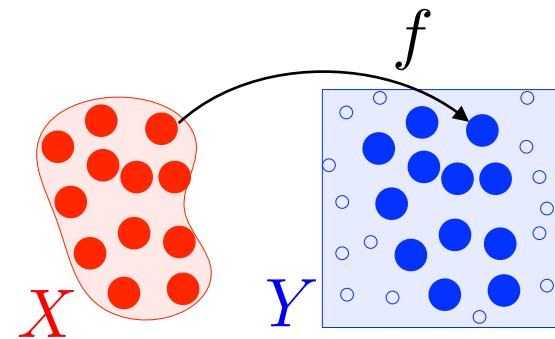
$$\mu = \sum_i \mu_i \delta_{x_i} \in \mathcal{M}_+^1(X) \quad d_{i,i'} = d(x_i, x_{i'})$$

$$\nu = \sum_j \nu_j \delta_{y_j} \in \mathcal{M}_+^1(Y) \quad \bar{d}_{j,j'} = \bar{d}(y_j, y_{j'})$$



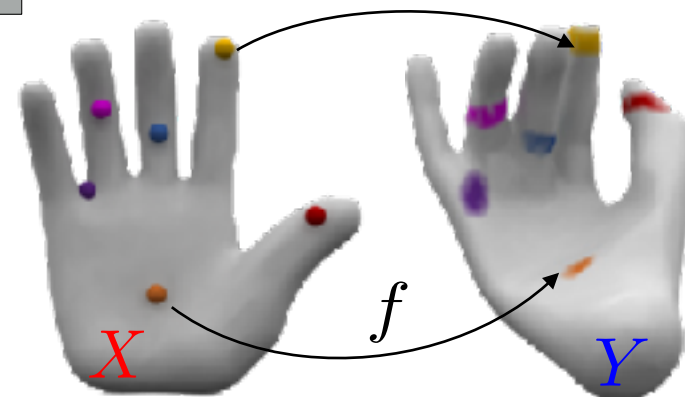
Def. Metric-measured spaces $(X, \mu, d) \in \mathbb{M}$:
 $\mu \in \mathcal{M}_+^1(X)$ and d is a distance on X

Def. Isometries on \mathbb{M} : $(\mu, d) \sim (\nu, \bar{d})$
 $\iff \exists f : X \rightarrow Y, \begin{cases} f_{\#}\mu = \nu, \\ d(x, x') = \bar{d}(f(x), f(x')). \end{cases}$



Prop. GW defines a distance on \mathbb{M}/\sim .
 [Memoli 2011]

\longrightarrow “bending-invariant” objects recognition.



For Arbitrary Spaces

Metric-measure spaces (X, Y) : $(d_X, \mu), (d_Y, \nu)$

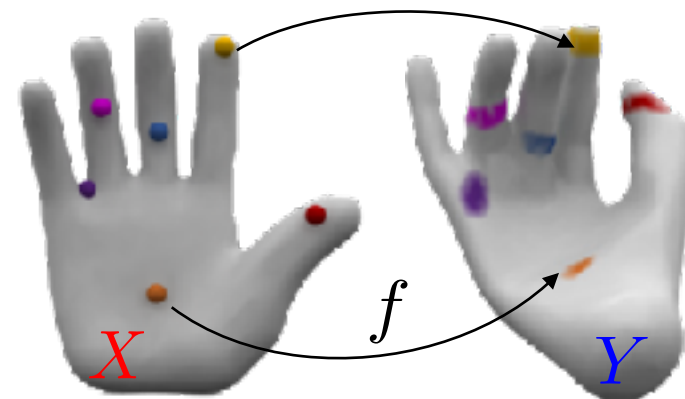
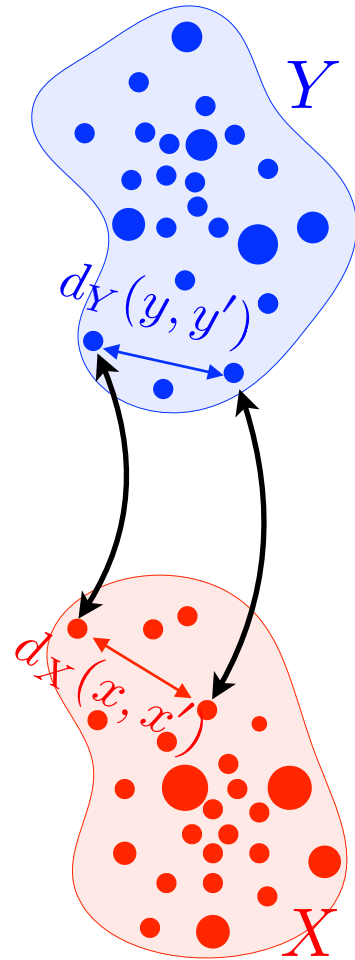
Def. Gromov-Wasserstein distance:

$$\text{GW}_2^2(d_X, \mu, d_Y, \nu) \stackrel{\text{def.}}{=} \min_{\pi \in \Pi(\mu, \nu)} \int_{X^2 \times Y^2} |d_X(x, x') - d_Y(y, y')|^2 d\pi(x, y) d\pi(x', y')$$

[Sturm 2012] [Memoli 2011]

Prop. GW is a distance on mm-spaces/isometries.

- “bending-invariant” objects recognition.
- QAP: NP-hard in general.
- need for a fast approximate solver.



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Entropic Gromov Wasserstein

Def. *Entropic Gromov-Wasserstein*

$$\text{GW}_{p,\varepsilon}^p(d, \mu, \bar{d}, \nu) \stackrel{\text{def.}}{=} \min_{T \in \mathcal{C}_{\mu,\nu}} \mathcal{E}_{d,\bar{d}}^p(T) - \varepsilon H(T)$$

Def. *Projected mirror descent:*

$$T \leftarrow \text{Proj}_{\mathcal{C}_{\mu,\nu}}^{\text{KL}} \left(T \odot e^{-\tau(-\nabla \mathcal{E}_{d,\bar{d}}^p(T) - \varepsilon \nabla H(T))} \right)$$

where $\text{Proj}_{\mathcal{C}_{\mu,\nu}}^{\text{KL}}(K) \stackrel{\text{def.}}{=} \text{argmin}_T \{ \text{KL}(T|K) ; T \in \mathcal{C}_{\mu,\nu} \}$

Prop. for $\tau = 1/\varepsilon$, the iteration reads

$$T \leftarrow \text{Sinkhorn}(\mu, \nu, -d \times T \times \bar{d})$$

Prop. T converges to a stationary point.

func $T = \text{GW}(C, \bar{C}, p, q)$

initialization:

$$T \leftarrow \mu \nu^\top$$

repeat:

$$D \leftarrow -d \times T \times \bar{d}$$

$$T \leftarrow \text{Sinkhorn}(\mu, \nu, D)$$

until convergence.

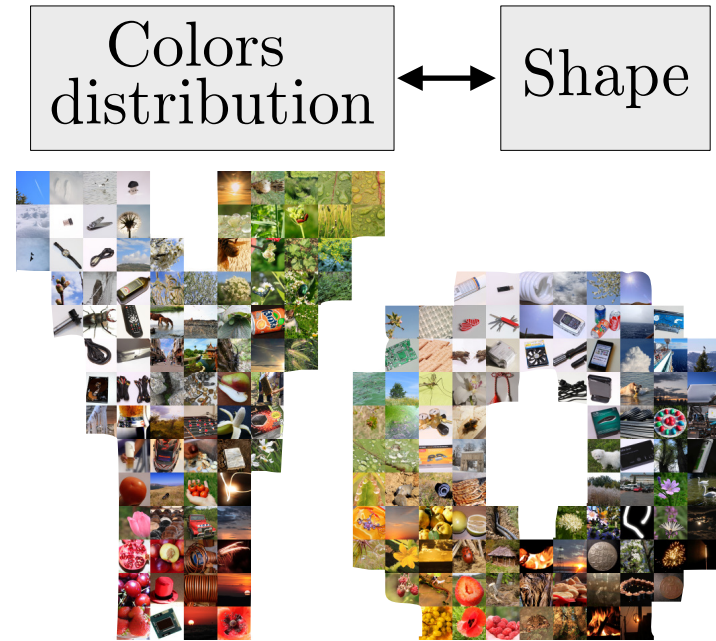
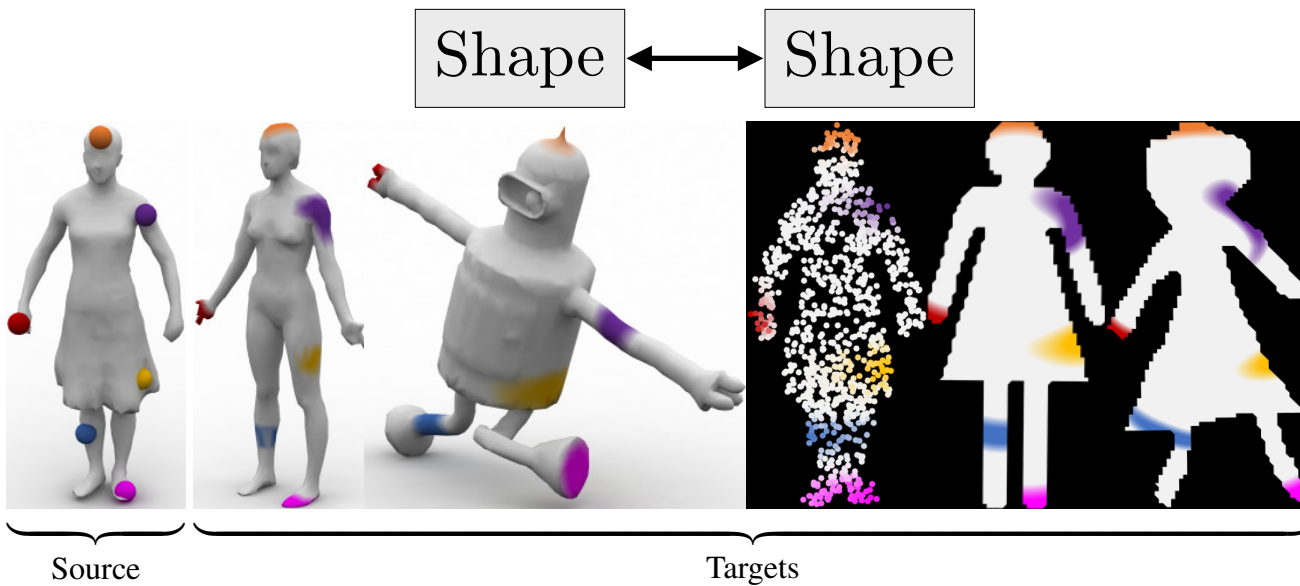
return T

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Applications of GW: Shapes Analysis

Use T to define registration between:



Shapes
 $(X_s)_s$

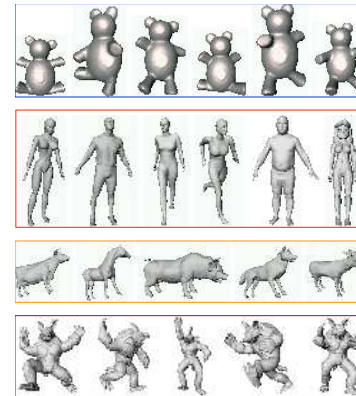
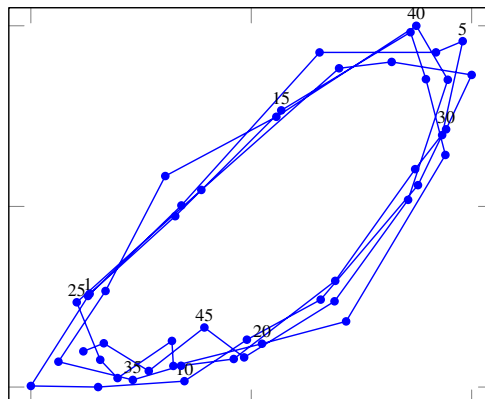
Geodesic distances
 $d_s = (D_{X_s}(x_i, x_{i'}))_{i,i'}$

GW distances
 $(GW_\epsilon(d_s, d_{s'}))_{s,s'}$

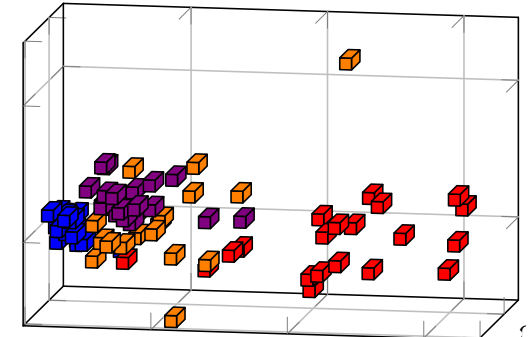
MDS
Visualization



MDS in 2-D



MDS in 3-D



Applications of GW: Quantum Chemistry

Input: Molecules with positions and charges $\mu = \sum_i \mu_i \delta_{x_i}$.

Regression problem: approximate ground state energy $\mu \mapsto f(\mu)$.
 $\rightarrow f$ by solving DFT approximation is too costly.

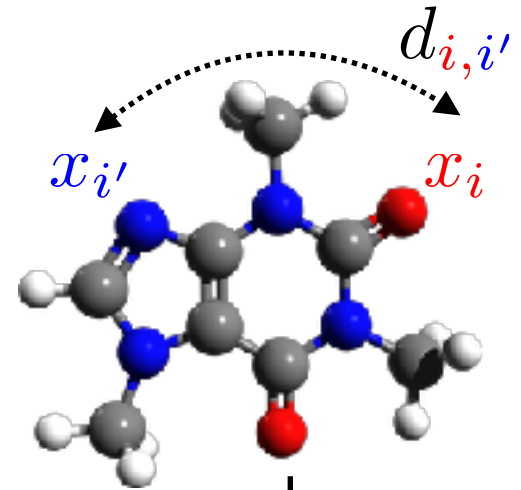
Coulomb matrices $d = d(\mu)$:

$$d_{i,i'} \stackrel{\text{def.}}{=} \begin{cases} \frac{\mu_i \mu_{i'}}{\|x_i - x_{i'}\|} & \text{for } (i \neq i') \\ \frac{1}{2} \mu_i^{2.4} & \text{for } (i = i'). \end{cases}$$

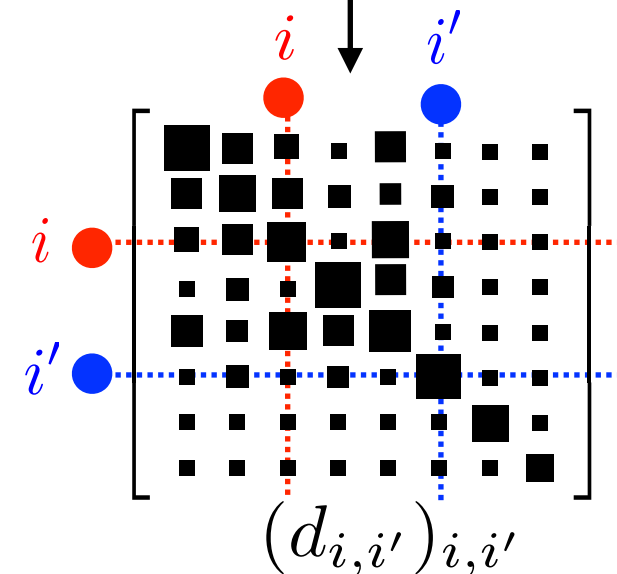
Learning: $(\mu_s, f(\mu_s))_s \rightarrow$ approximation \tilde{f} .

GW-interpolation: $\tilde{f}(\mu) = f(\mu_{s^*})$

$$s^* = \operatorname{argmin}_s \operatorname{GW}(d(\mu), d(\mu_s))$$



[Rupp et al 2012]



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Gromov-Wasserstein Geodesics

Def. *Gromov-Wasserstein Geodesic*

$$(\mu_t, d_t) \in \underset{(\mu, d) \in \mathbb{X}}{\operatorname{argmin}} (1 - t) \operatorname{GW}_2^2(\mu_0, d_0, \mu, d) + t \operatorname{GW}_2^2(\mu_1, d_1, \mu, d)$$

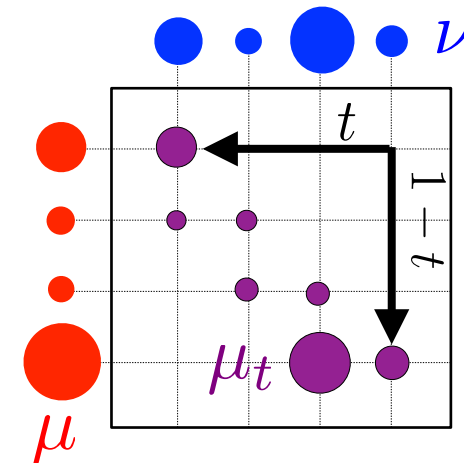
Optimal coupling T^* : $\operatorname{GW}_2^2(d_0, \mu_0, d_1, \mu_1) \stackrel{\text{def.}}{=} \mathcal{E}_{d_0, d_1}^2(T^*)$

Prop. One can define (μ_t, d_t) on $X \times Y$ as

$$\mu_t = \sum_{i,j} T_{i,j}^* \delta_{x_i, y_j}$$

$$d_t((x, y), (x', y')) = (1 - t) d_0(x, x') + t d_1(y, y')$$

[Sturm 2012]



→ $X \times Y$ is not practical for most applications.

(need to fix the size of the geodesic embedding space)

→ Extension to more than 2 input spaces?

Gromov-Wasserstein Barycenters

Input: | Measures $(\mu_s)_s$, matrices $(d_s)_s$
 | Weights λ , size N , $\mu \in \mathbb{R}_+^N$ probability vector

Def. GW Barycenters

$$\min_{d \in \mathbb{R}^{N \times N}} \sum_s \lambda_s \text{GW}_{2,\varepsilon}^2(d_s, \mu_s, d, \mu)$$

$$\min_{d, (T_s)_s} \left\{ \sum_s \lambda_s (\mathcal{E}_{d,d_s}^2(T_s) - \varepsilon H(T_s)) ; \forall s, T_s \in \mathcal{C}_{\mu, \mu_s} \right\}$$

Alternating minimization:

func $C = \text{GW-bary}(d_s, \mu_s, \mu)_s$

initialization: $C \leftarrow C_0$

repeat:

for $s = 1$ to S do

On $T_s \rightarrow T_s \leftarrow \text{GW}(d, \mu, d_s, \mu_s)$

On $d \rightarrow d \leftarrow \frac{1}{\mu \mu^\top} \sum \lambda_s T_s^\top d_s T_s$

until convergence.

return C

