

Numerical Optimal Transport

<http://optimaltransport.github.io>

Density Fitting

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ENS
ÉCOLE NORMALE
SUPÉRIEURE



Weak vs Strong Topology

Random vectors

$$\mathbb{P}(X \in A)$$

Convergence in law:

\forall set A

$$\mathbb{P}(X_n \in A) \xrightarrow{n \rightarrow +\infty} \mathbb{P}(X \in A)$$

Radon measures

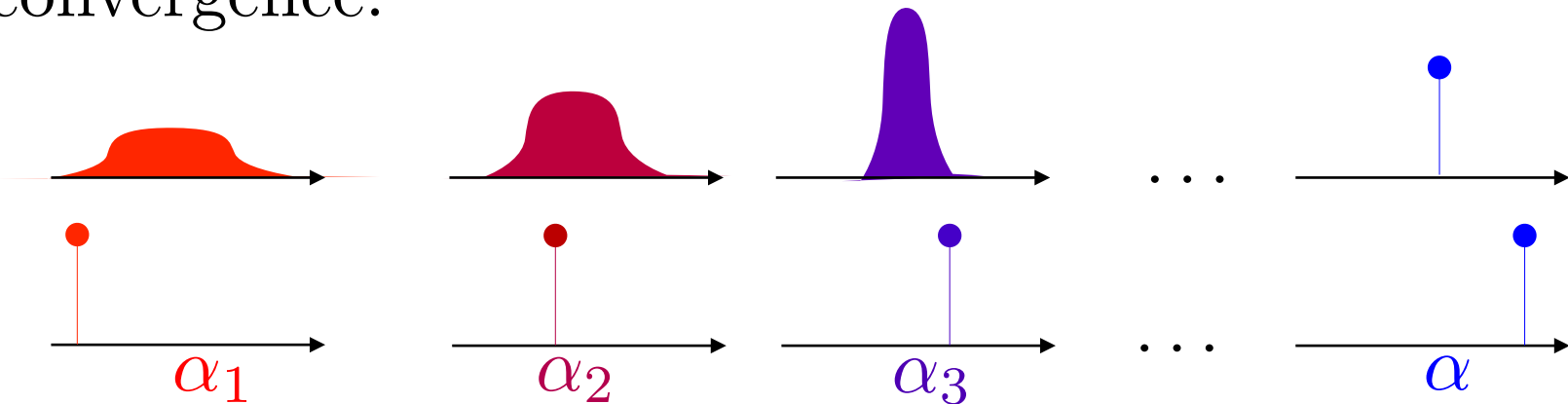
$$\int_A d\alpha(x)$$

Weak* convergence:

\forall continuous function f

$$\int f d\alpha_n \xrightarrow{n \rightarrow +\infty} \int f d\alpha$$

Weak convergence:



Key question: quantifying weak convergence.

Central Limit Theorem

Central limit theorem: If $\mathbb{E}(X) = 0$, $\mathbb{E}(X^2) = 1$ and $(X_i)_i \stackrel{\text{i.i.d.}}{\sim} X$

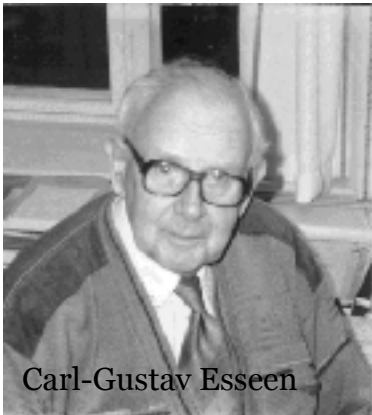
$$Y_n \stackrel{\text{def.}}{=} \frac{X_1 + \dots + X_n}{\sqrt{n}} \xrightarrow{\text{law}} \mathcal{N}(0, 1)$$

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Kolmogorov-Smirnov distance: $d_{KS}(X, Y) \stackrel{\text{def.}}{=} \max_t |\mathbb{P}(X \leq t) - \mathbb{P}(Y \leq t)|$



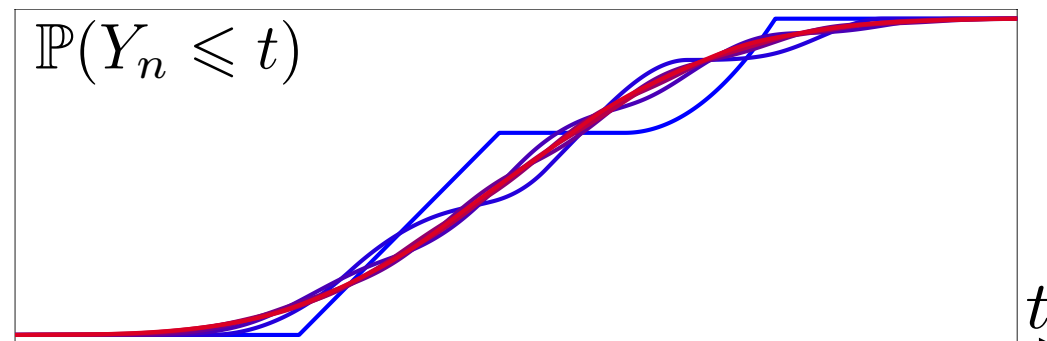
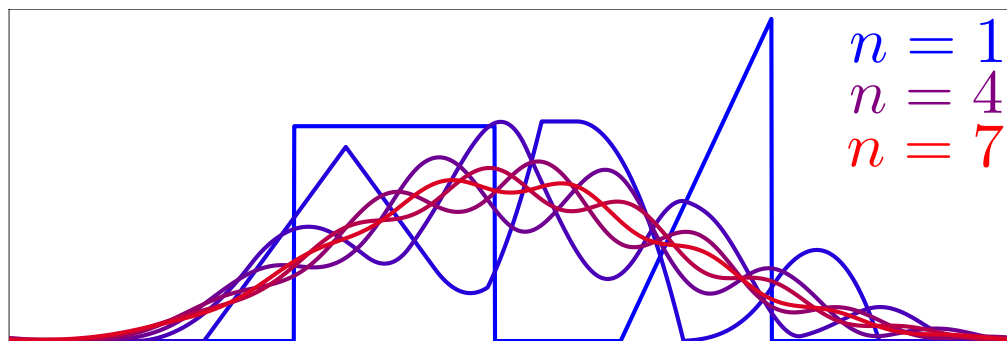
Metatrizes convergence in law: $X \xrightarrow{\text{law}} Y \Leftrightarrow d_{KS}(X, Y) \rightarrow 0$

Theorem:

[Berry 1941]

[Esseen, 1942]

$$d_{KS}(Y_n, \mathcal{N}(0, 1)) \leq \frac{C\mathbb{E}(|X|^3)}{\sqrt{n}} \quad C \leq 1/2$$

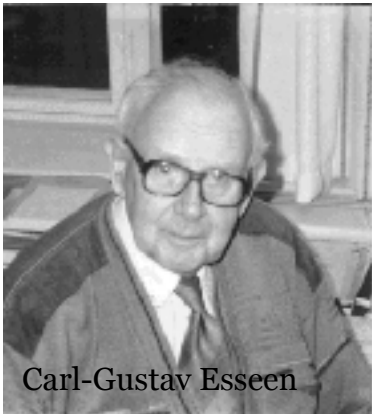


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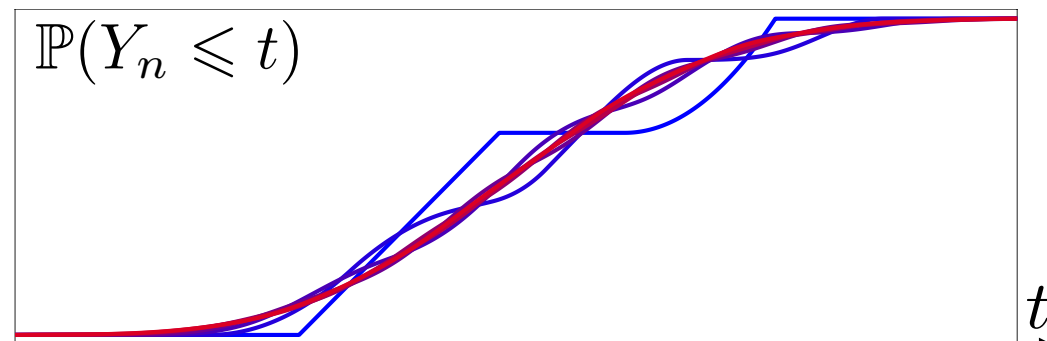
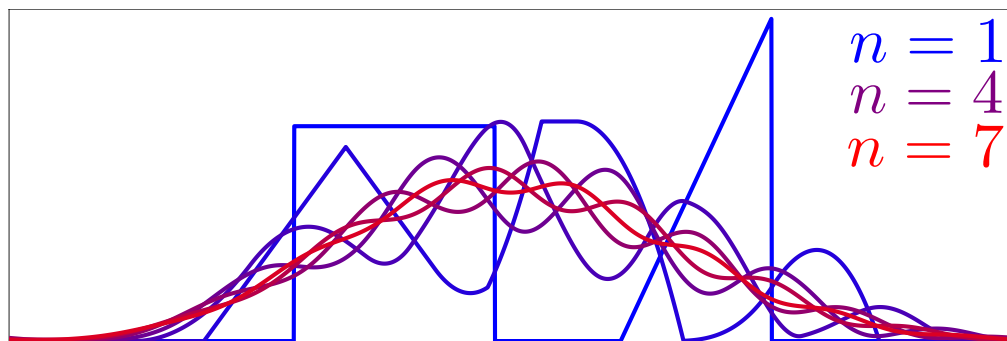
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Multi-dimensional extension: use W_1 in place of d_{KS} !

Overview

- **Csiszar Divergences**
- Dual Norms and MMD
- Minimum Kantorovitch Estimators
- Deep Generative Models Fitting

Strong Norms

Reference measure dx on \mathcal{X} .

L^p norms on densities:

$$D(\alpha, \beta) \stackrel{\text{def.}}{=} \left(\int_{\mathcal{X}} \left(\frac{d\alpha}{dx}(x) - \frac{d\beta}{dx}(x) \right)^p dx \right)^{1/p} = \left\| \frac{d\alpha}{dx} - \frac{d\beta}{dx} \right\|_{L^p(dx)}$$

→ defined only if $\alpha \ll dx$ and $\beta \ll dx$.

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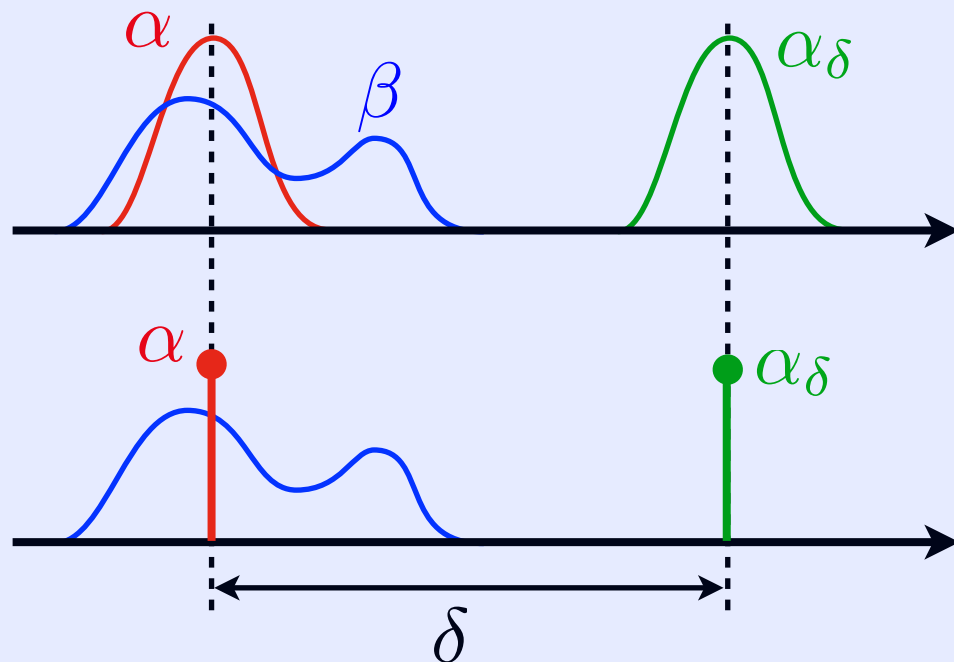
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Metrizes the strong topology.

$$\alpha_\delta \xrightarrow{\text{weak}} \alpha$$

$$D(\alpha, \alpha_\delta) \approx \text{cst}$$

$$W_p(\alpha, \alpha_\delta) = \delta$$



Csiszar Divergence



Comparing

$$\frac{d\alpha}{dx} \leftrightarrow \frac{d\beta}{dx}$$



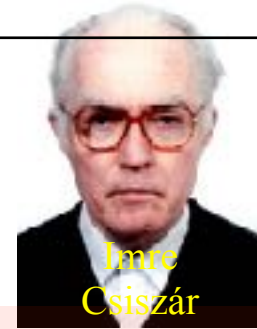
$$\frac{d\alpha}{d\beta} \leftrightarrow 1$$

Csiszár φ -divergence: $\mathcal{D}_\varphi(\alpha|\beta) \stackrel{\text{def.}}{=} \int_{\mathcal{X}} \varphi\left(\frac{d\alpha}{d\beta}\right) d\beta + \varphi'_\infty \alpha^\perp(\mathcal{X})$

φ convex, $\varphi(1) = 0$, $\varphi \geq 0$ \rightarrow Important if $\alpha(\mathcal{X}) \neq \beta(\mathcal{X})$.

Proposition: $\mathcal{D}_\varphi \geq 0$ is convex, $\mathcal{D}_\varphi(\alpha|\beta) = 0 \Leftrightarrow \alpha = \beta$.

Csiszar Divergence



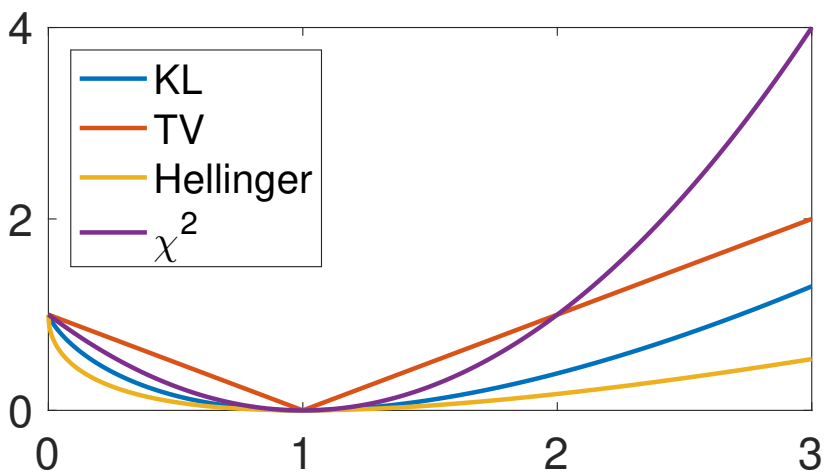
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$$\frac{d\alpha}{dx} \leftrightarrow \frac{d\beta}{dx} \longrightarrow \frac{d\alpha}{d\beta} \leftrightarrow 1$$

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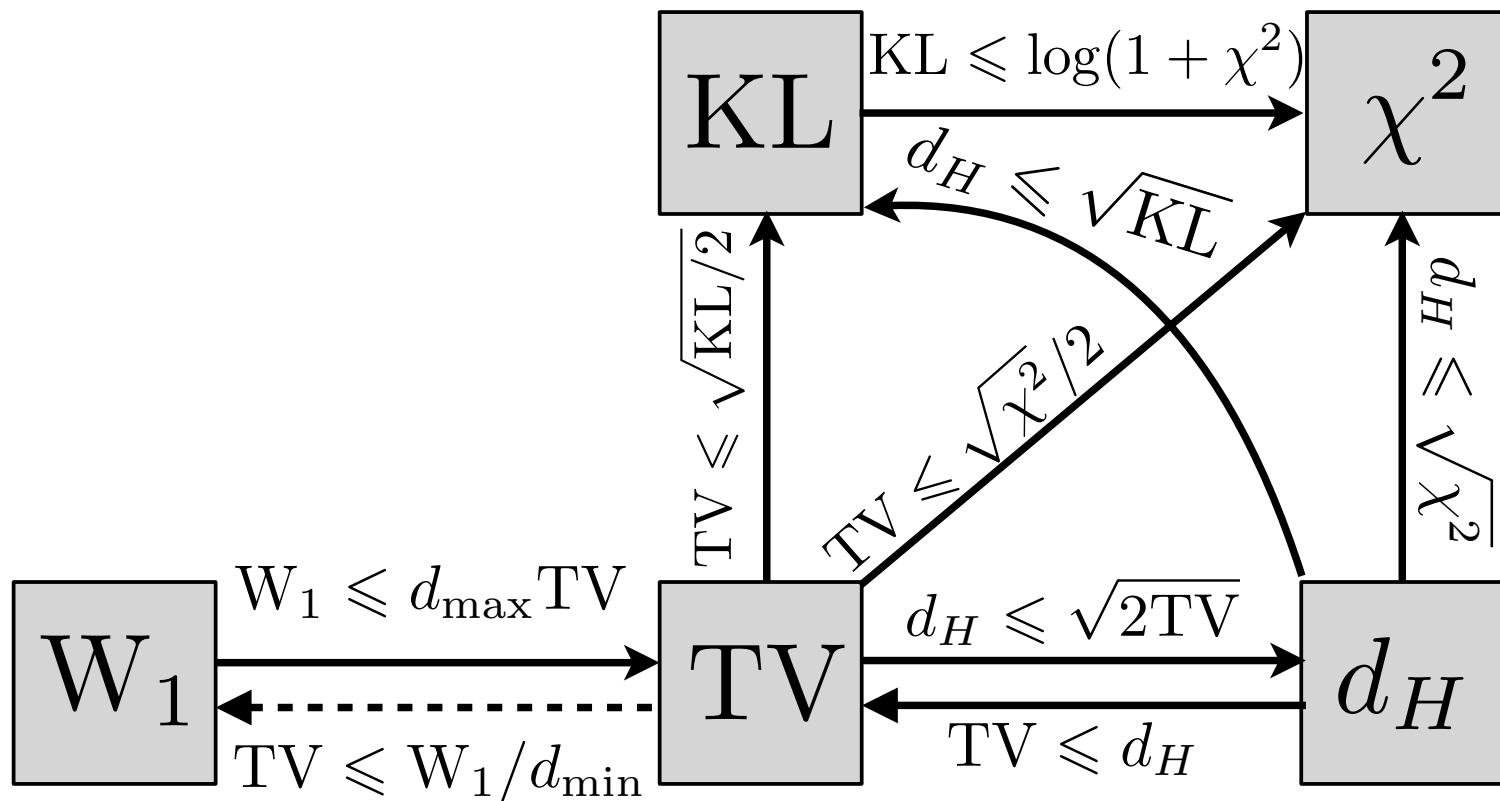


$ s - 1 ^2$	χ^2
$ s - 1 $	TV norm
$s \log(s) - s + 1$	Generalized KL
$ \sqrt{s} - 1 ^2$	Hellinger distance
$s \log(s)$	KL

$$\|\alpha - \beta\|_{\text{TV}} = \left\| \frac{d\alpha}{dx} - \frac{d\beta}{dx} \right\|_{L^1(dx)}$$

$$d_{\text{H}}(\alpha, \beta) = \left\| \sqrt{\frac{d\alpha}{dx}} - \sqrt{\frac{d\beta}{dx}} \right\|_{L^2(dx)}^2$$

Equivalence and non-equivalence



$$d_{\max} = \sup_{(x, x')} d(x, x')$$

$$d_{\min} \stackrel{\text{def.}}{=} \min_{x \neq x'} d(x, x')$$

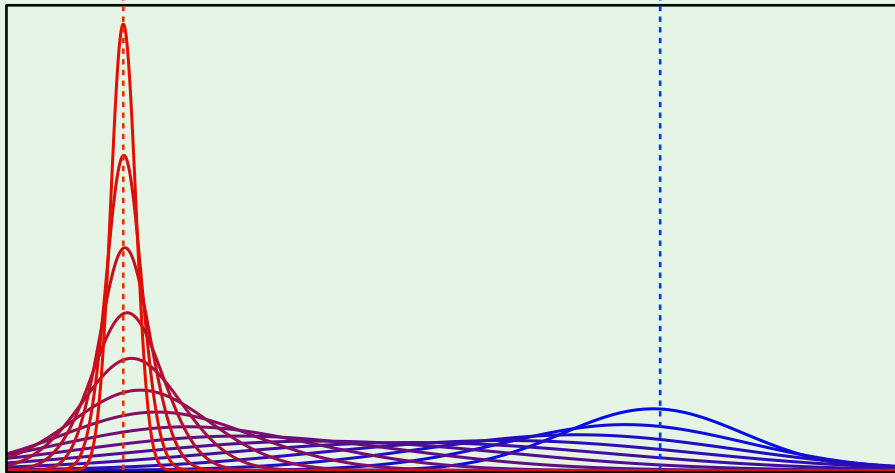
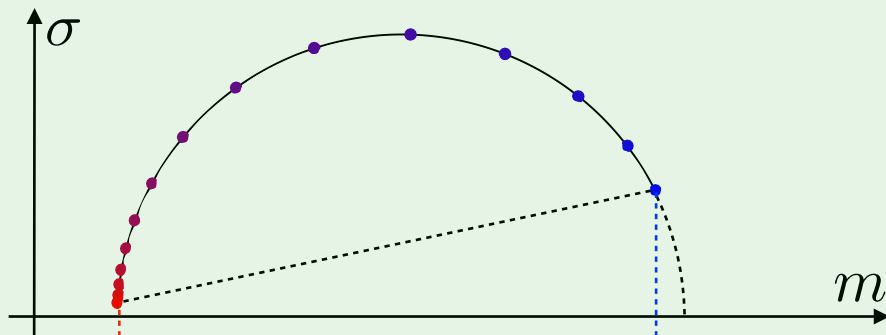
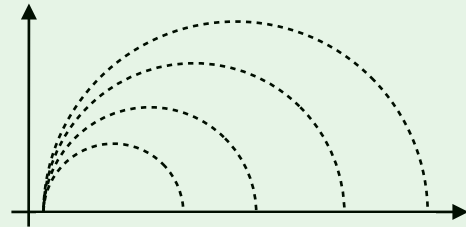
OT vs. KL (Fisher-Rao)

$$\mathcal{X} = \mathbb{R} \quad \alpha = \mathcal{N}(m_\alpha, \sigma_\alpha), \quad \beta = \mathcal{N}(m_\beta, \sigma_\beta)$$

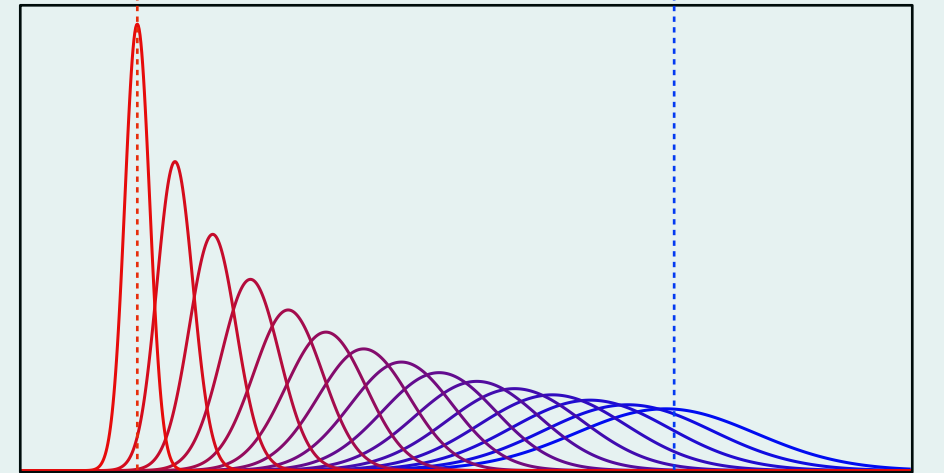
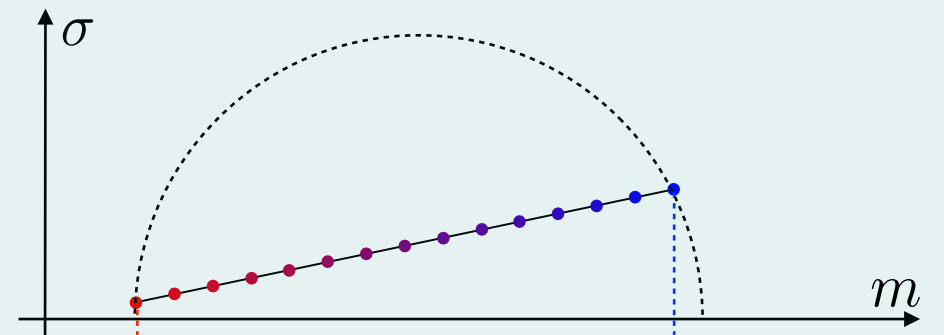
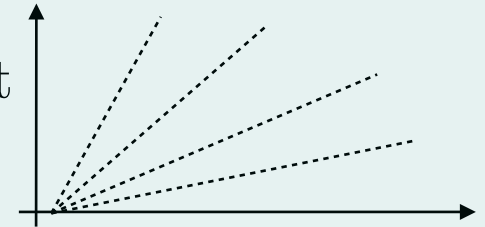
$$\text{KL}(\alpha|\beta) = \frac{1}{2} \left(\frac{\sigma_\alpha^2}{\sigma_\beta^2} + \log \left(\frac{\sigma_\beta^2}{\sigma_\alpha^2} \right) + \frac{|m_\alpha - m_\beta|}{\sigma_\beta} - 1 \right)$$

$$W_2^2(\alpha, \beta) = |m_\alpha - m_\beta|^2 + |\sigma_\alpha - \sigma_\beta|^2$$

Fisher-Rao
(hyperbolic)



Optimal Transport
(Euclidean)



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Dual Norms

Dual norms: (aka Integral Probability Metrics)

$$\|\alpha - \beta\|_B \stackrel{\text{def.}}{=} \max \left\{ \int_{\mathcal{X}} f(x) (d\alpha(x) - d\beta(x)) ; f \in B \right\}$$

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$$\text{TV: } B = \{f ; \|f\|_{\infty} \leq 1\}.$$

$$\text{Wasserstein 1: } B = \{f ; \|\nabla f\|_{\infty} \leq 1\}.$$

$$\text{Flat norm: } B = \{f ; \|f\|_{\infty} \leq 1, \|\nabla f\|_{\infty} \leq 1\}.$$

$$\text{Negative Sobolev: } B = \{f ; k = 0, \dots, s, \|\partial^k f\|_{L^2(\mathbb{R}^d)} \leq 1\}$$

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$$\|\alpha\|_B \rightarrow 0 \quad \iff \quad \alpha \xrightarrow{\text{weak}} 0$$

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$$\|\delta_x - \delta_y\|_{\text{TV}} = 2 \quad \text{if } x \neq y$$



$f \in B$ needs to regular
(e.g. $s > d/2$)

Hilbertian Norms on Measures

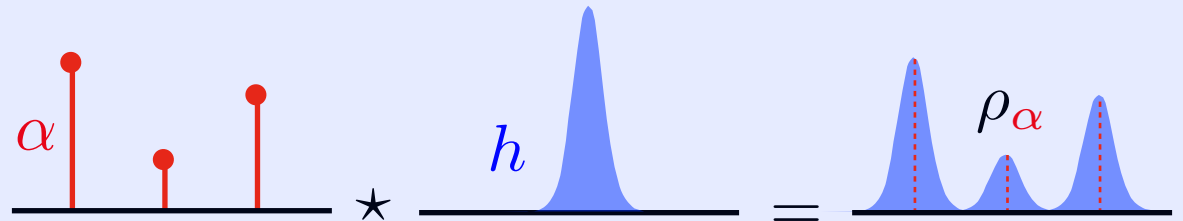
In $\mathcal{X} = \mathbb{R}^d$, smoothing with convolution:

$$\alpha \xrightarrow{\star h} \alpha \star h = \rho_\alpha dx \quad \rho_\alpha(x) \stackrel{\text{def.}}{=} \int_{\mathbb{R}^d} h(x-y) d\alpha(y)$$

$$\alpha = \sum_i \mathbf{a}_i \delta_{x_i}$$

$\star h \downarrow$

$$\rho_\alpha = \sum_i \mathbf{a}_i h(\cdot - x_i)$$



Hilbertian Norms on Measures

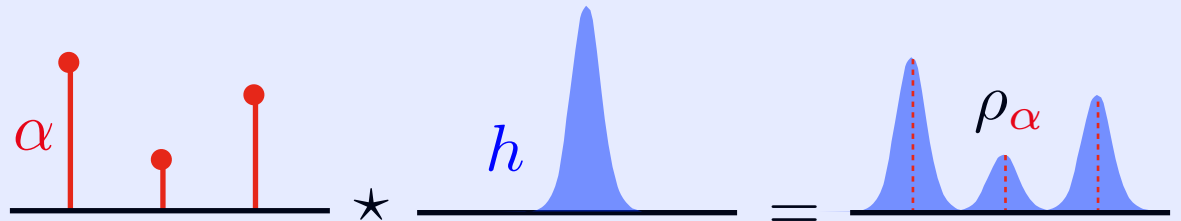
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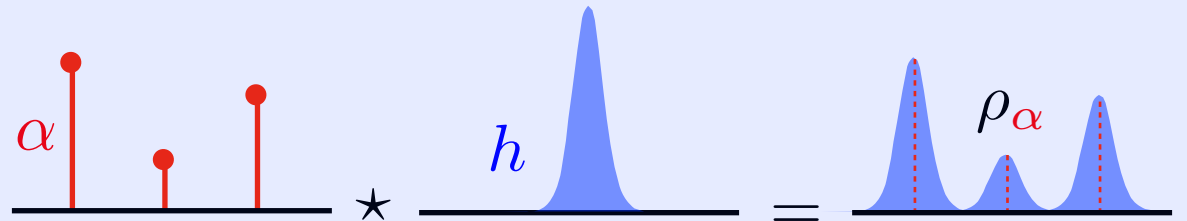
Hilbertian norm: $\|\alpha - \beta\|_k^2 \stackrel{\text{def.}}{=} \|\rho_\alpha - \rho_\beta\|_{L^2(dx)}^2$

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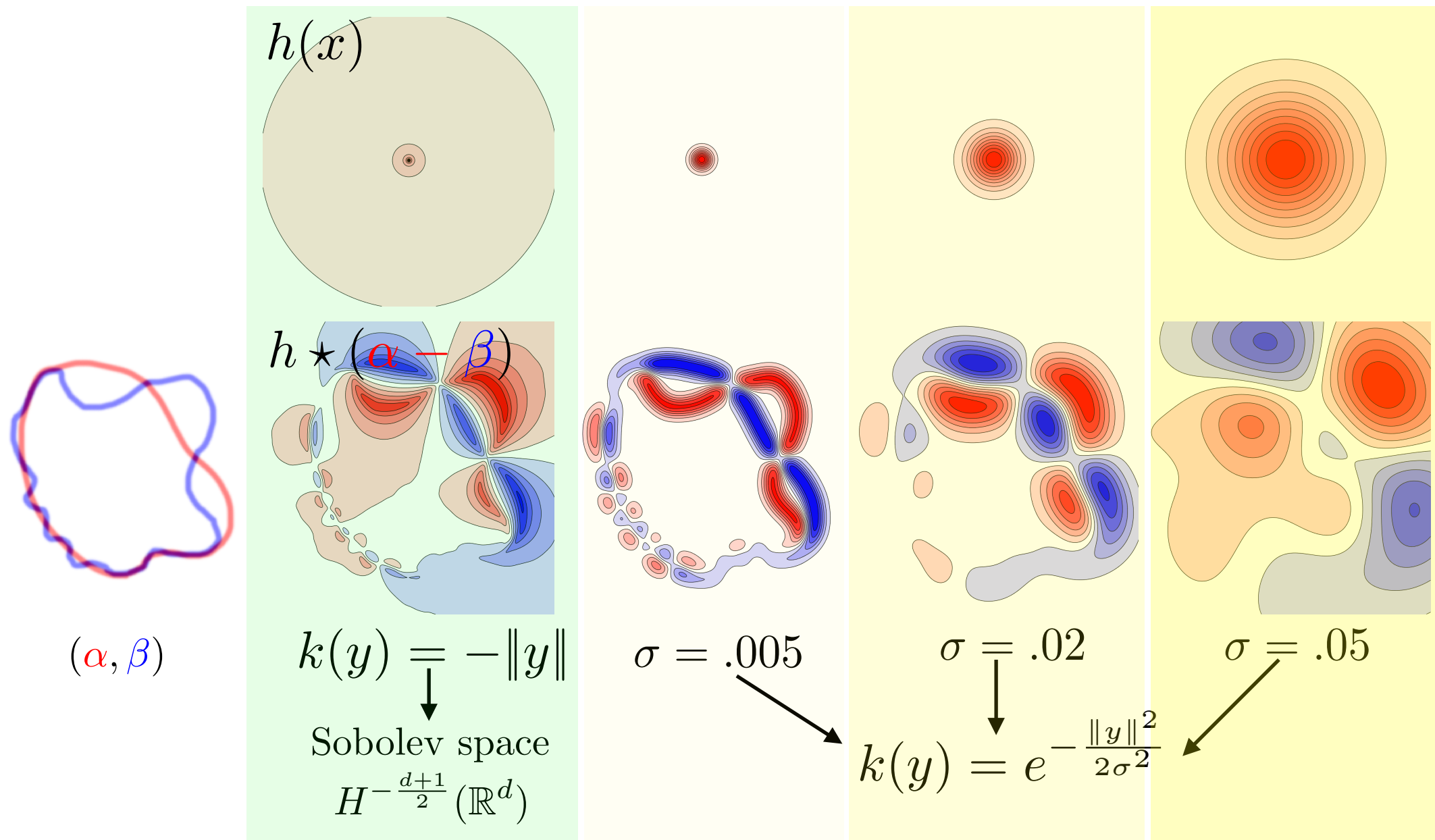


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Kernel expression:
$$\begin{aligned} \|\xi\|_k^2 &= \int_{\mathbb{R}^d} \left(\int_{\mathbb{R}^d} h(x-y) d\xi(y) \right)^2 dx \\ &= \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} k(y-y') d\xi(y') d\xi(y) \end{aligned}$$

Correlation kernel: $k(y) \stackrel{\text{def.}}{=} \int_{\mathbb{R}^d} h(x-y) h(x) dx$

Comparison of Kernels



Maximum Mean Discrepancies

$$\|\xi\|_k^2 = \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} k(y - y') d\xi(y') d\xi(y)$$

Theorem: if $\hat{k}(\omega) > 0$, $\|\cdot\|_k$ metrizes weak convergence.

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→ Extends to general \mathcal{X} using positive kernels (MMD).

MMD:
$$\begin{aligned} \|\xi\|_k^2 &\stackrel{\text{def.}}{=} \int_{\mathcal{X} \times \mathcal{X}} k(x, y) d\xi(x) d\xi(y) \\ &= \mathbb{E}(k(X, Y)), (X, Y) \sim \xi \text{ indep.} \end{aligned}$$

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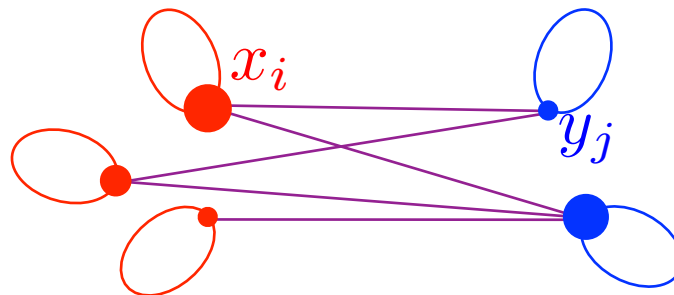
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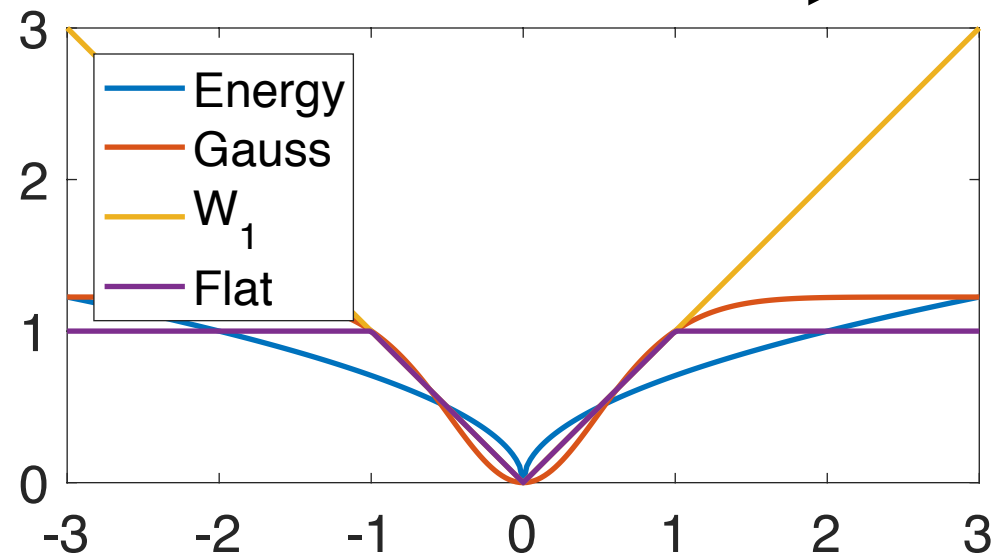
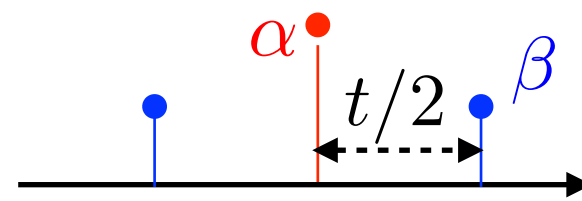
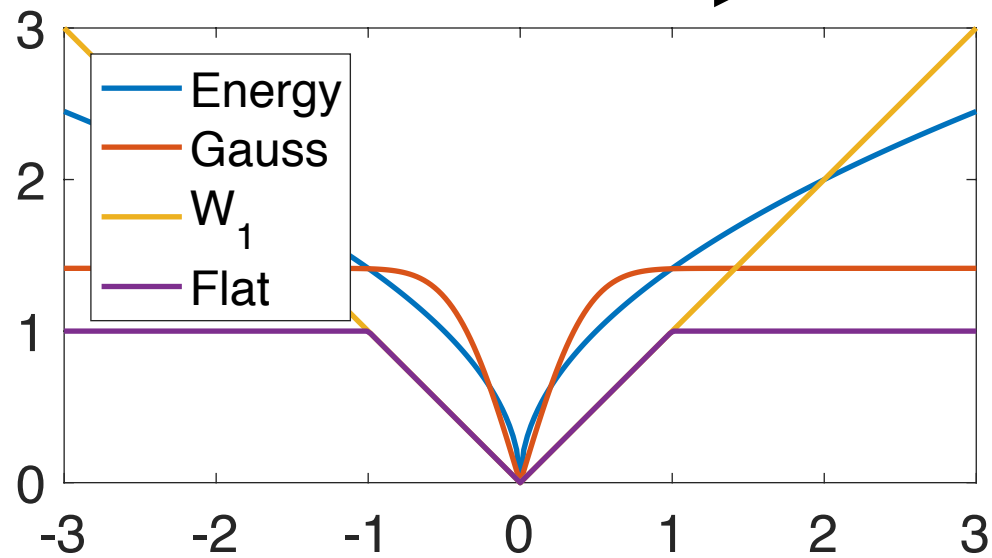
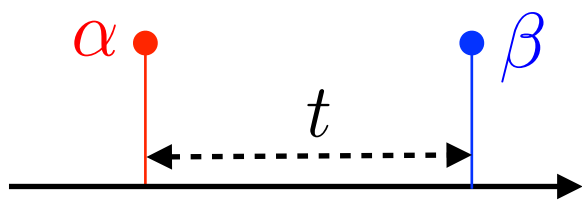
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$$\alpha = \sum_{i=1}^n \mathbf{a}_i \delta_{x_i} \quad \beta = \sum_{j=1}^m \mathbf{b}_j \delta_{y_j}$$

$$\|\alpha - \beta\|^2 = \sum_{i, i'} \mathbf{a}_i \mathbf{a}_{i'} k(x_i, x_{i'}) - 2 \sum_{i, j} \mathbf{a}_i \mathbf{b}_j k(x_i, y_j) + \sum_{j, j'} \mathbf{b}_j \mathbf{b}_{j'} k(y_j, y_{j'})$$



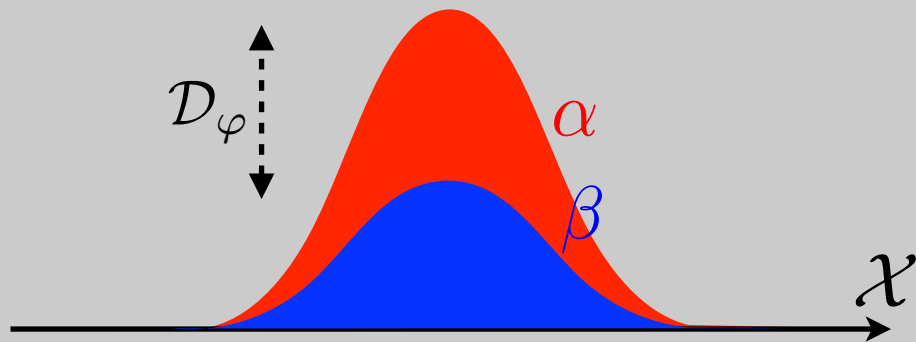
Comparison of Dual Norms



Csiszar Divergence vs Dual Norms

Csiszár divergences:

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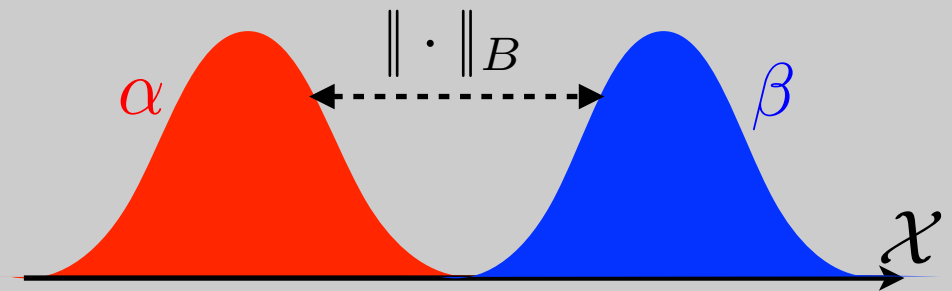


Strong topology

→ KL, TV, χ^2 , Hellinger ...

Dual norms:

$$\|\alpha - \beta\|_B \stackrel{\text{def.}}{=} \max_{f \in B} \int_{\mathcal{X}} f(x)(d\alpha(x) - d\beta(x))$$



Weak topology

→ W_1 , flat, RKHS*, energy dist, ...

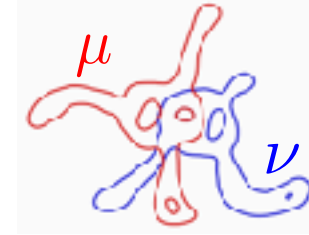
OT Loss for Diffeomorphic Registration

Joint work with J. Feydy, B. Charier, F-X. Vialard.

Shape registration:

$$\min_{\varphi \text{ diffeo}} D(\varphi(\mu), \nu) + R(\varphi)$$

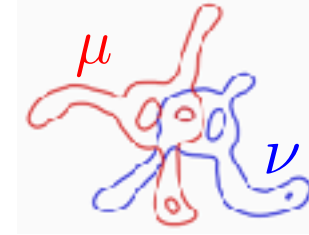
loss regularity



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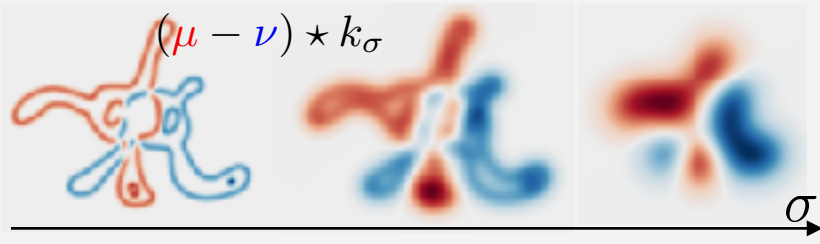
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Hilbertian loss (MMD/RKHS):

$$D(\mu, \nu) = \|k_\sigma \star (\mu - \nu)\|_{L^2}^2$$



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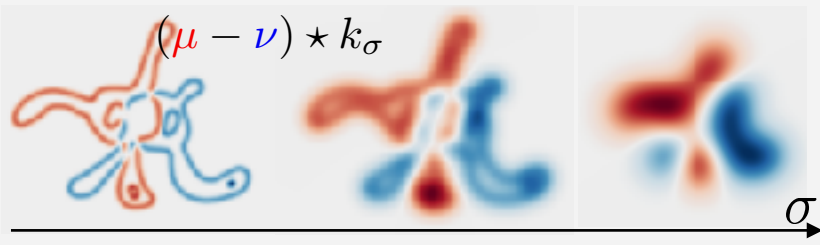
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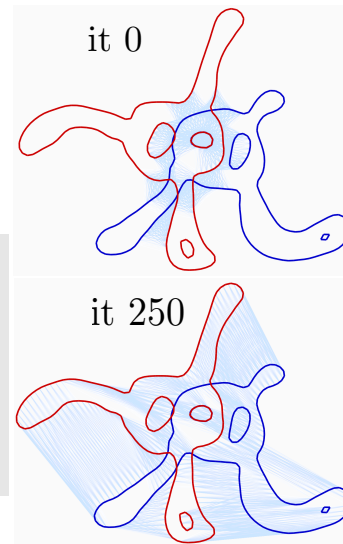
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Sinkhorn divergence:

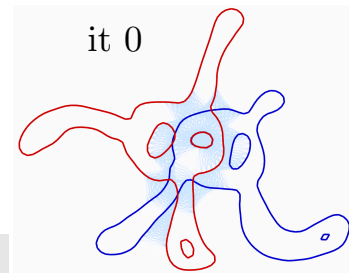
$$D(\mu, \nu) = \bar{W}_\varepsilon(\mu, \nu)$$



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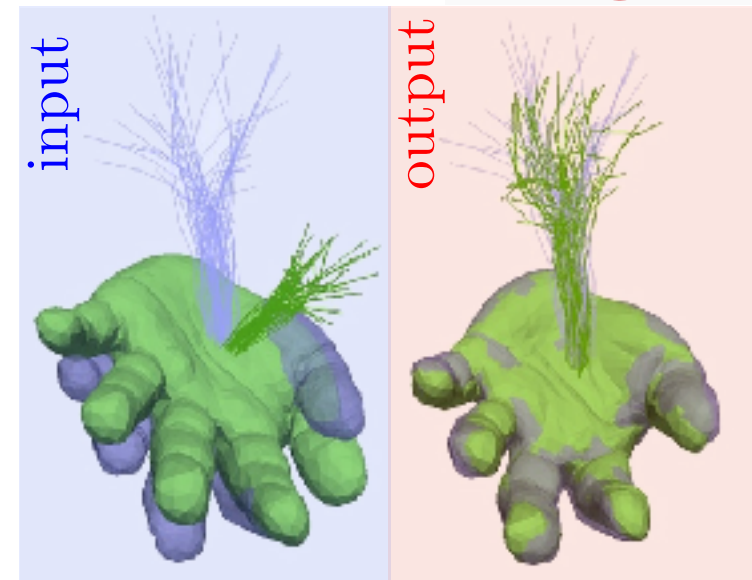
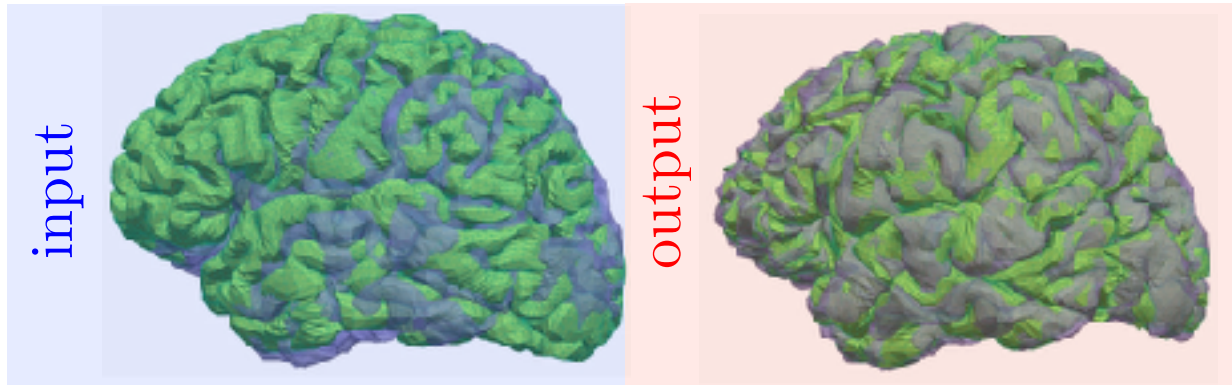
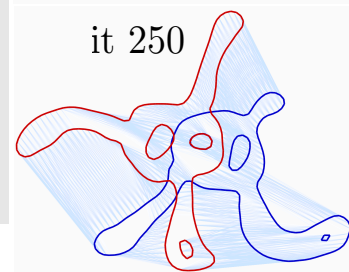
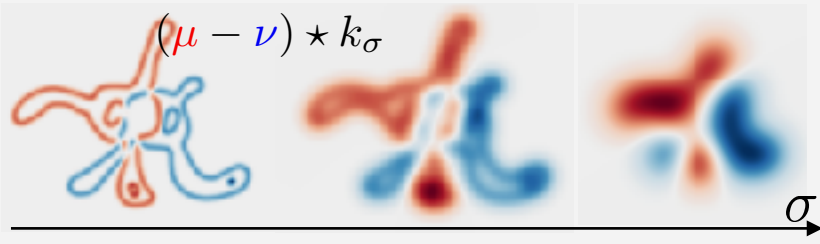


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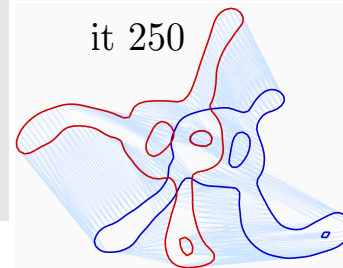
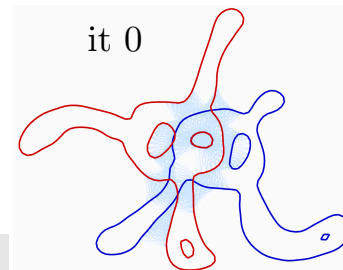
$$D(\mu, \nu) = \bar{W}_\varepsilon(\mu, \nu)$$



OT Loss for Diffeomorphic Registration

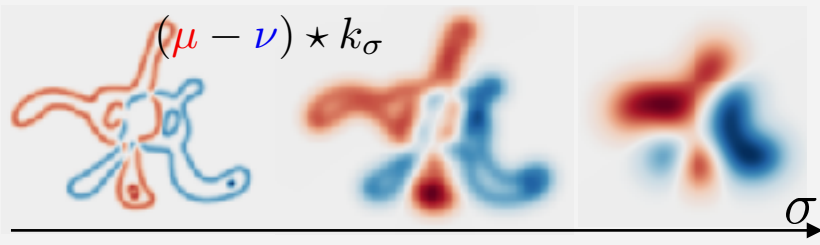
Joint work with J. Feydy, B. Charier, F-X. Vialard.

Shape registration: $\min_{\varphi \text{ diffeo}} D(\varphi(\mu), \nu) + R(\varphi)$
loss regularity



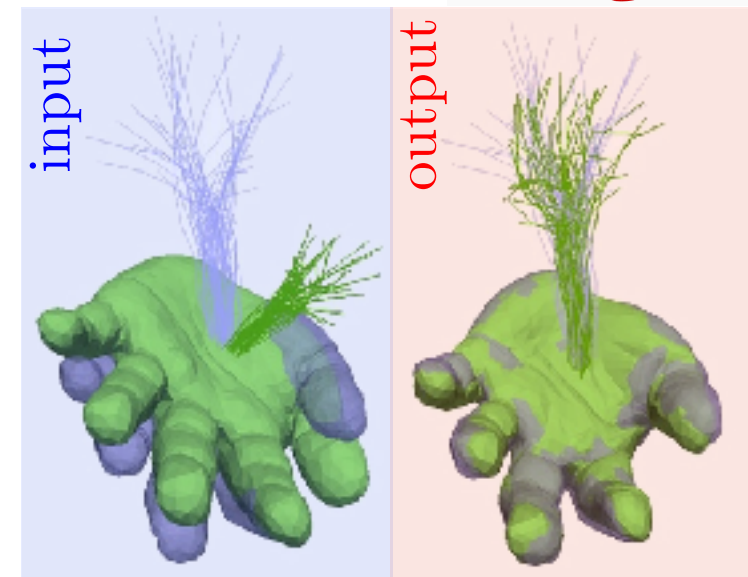
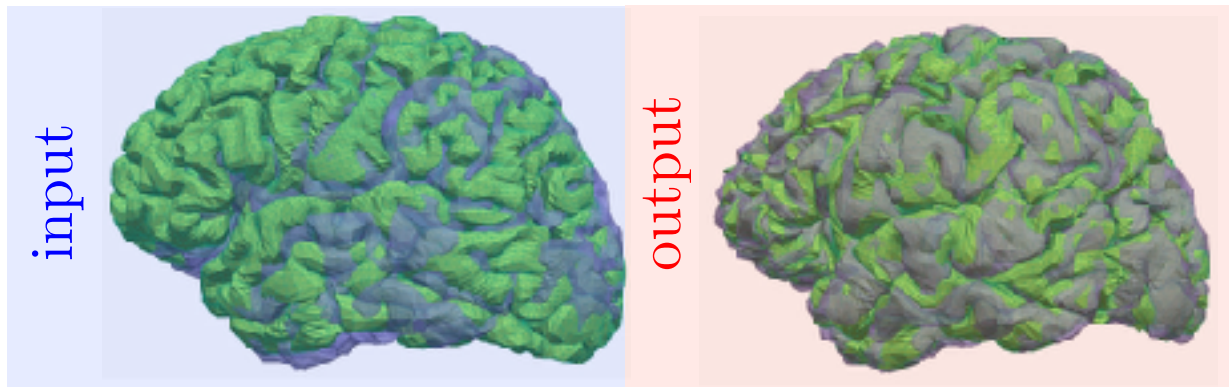
Hilbertian loss (MMD/RKHS):

$$D(\mu, \nu) = \|k_\sigma \star (\mu - \nu)\|_{L^2}^2$$



Sinkhorn divergence:

$$D(\mu, \nu) = \bar{W}_\varepsilon(\mu, \nu)$$



- Do not use OT for registration ... but as a loss.
- Sinkhorn's iterates “propagate” a small bandwidth kernel.
- Automatic differentiation: game changer for advanced loss and models.

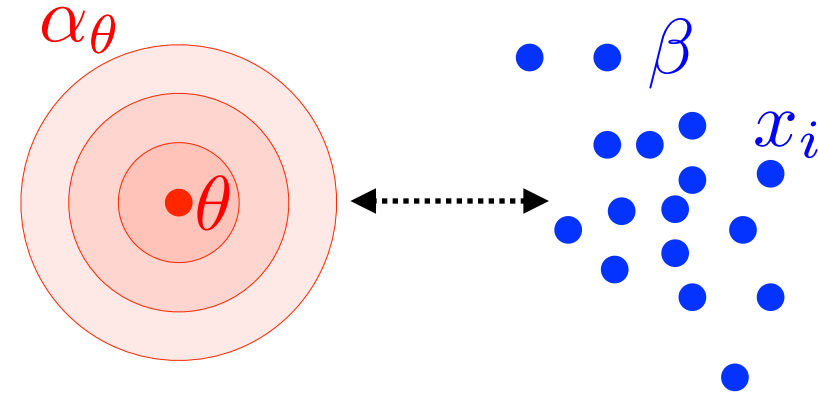
Overview

- Csiszar Divergences
- Dual Norms and MMD
- **Minimum Kantorovitch Estimators**
- Deep Generative Models Fitting

Density Fitting and Generative Models

Observations: $\beta \stackrel{\text{def.}}{=} \frac{1}{n} \sum_{i=1}^n \delta_{x_i}$

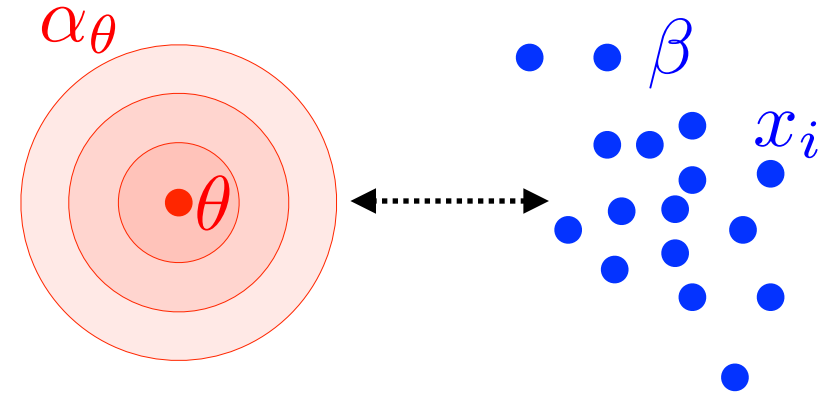
Parametric model: $\theta \mapsto \alpha_\theta$



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Parametric model: $\theta \mapsto \alpha_\theta$



Density fitting: $d\alpha_\theta(x) = \rho_\theta(x)dx$

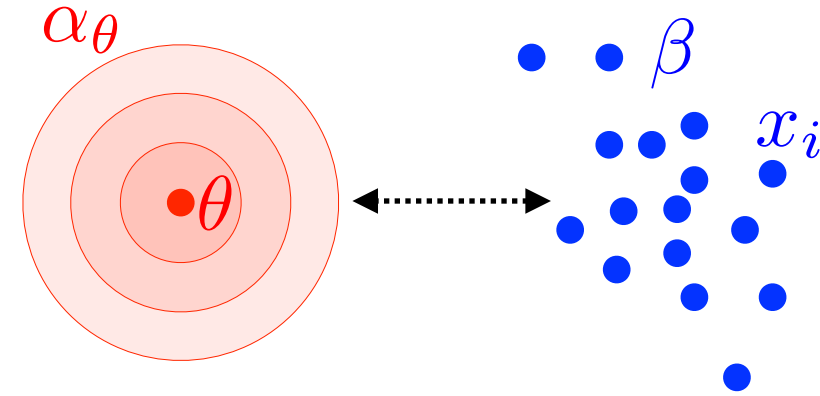
$$\min_{\theta} \widehat{\text{KL}}(\beta | \alpha_\theta) \stackrel{\text{def.}}{=} - \sum_i \log(\rho_\theta(x_i))$$

Maximum
likelihood (MLE)

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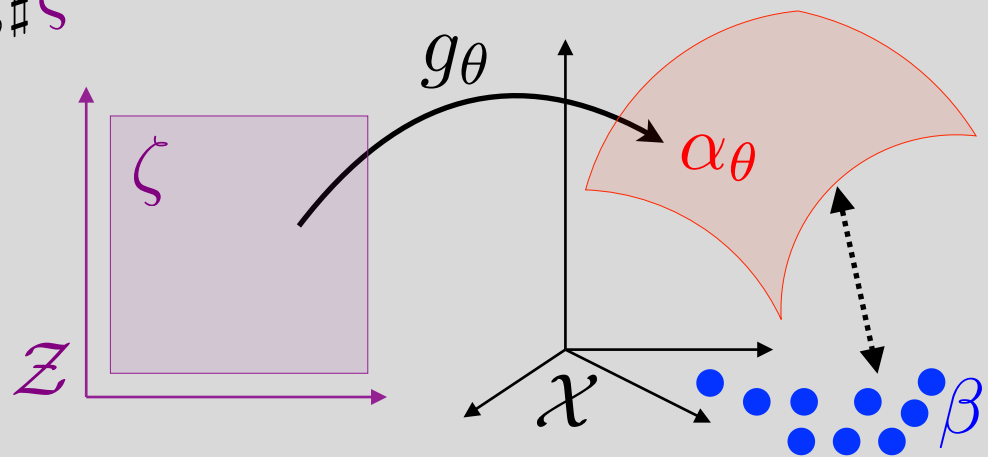
Maximum likelihood (MLE)

Generative model fit: $\alpha_\theta = g_{\theta, \#} \zeta$

$$\widehat{\text{KL}}(\beta | \alpha_\theta) = +\infty$$

→ MLE undefined.

→ Need a weaker metric.



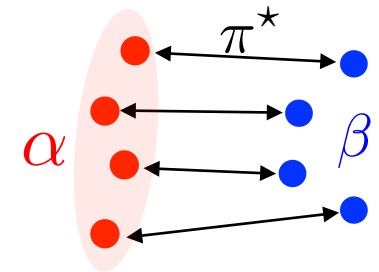
Loss Functions for Measures

Density fitting: $\min_{\theta} D(\alpha_{\theta}, \beta)$

$$\beta = \frac{1}{n} \sum_i \delta_{x_i}$$

Optimal Transport Distances

$$W_p^p(\alpha, \beta) \stackrel{\text{def.}}{=} \min_{\pi \in \mathcal{U}(\alpha, \beta)} \int d(x, y)^p d\pi(x, y)$$



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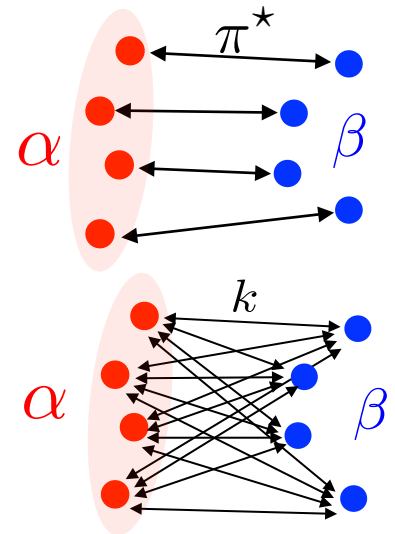
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Gaussian: $k(x, y) = e^{-\frac{\|x-y\|^2}{2\sigma^2}}$. Energy distance: $k(x, y) = -\|x - y\|^2$.



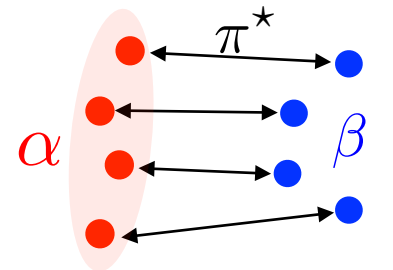
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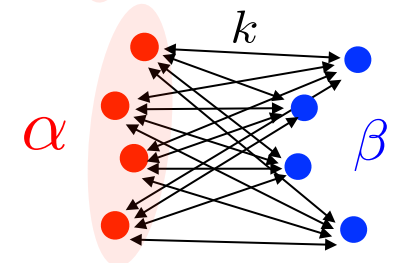
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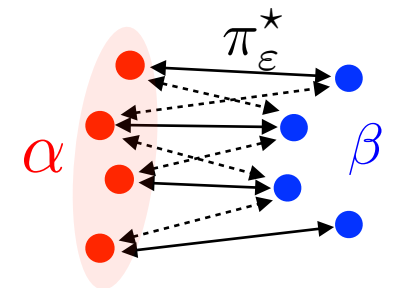
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Sinkhorn divergences [Genevay, Peyré, Cuturi 17]

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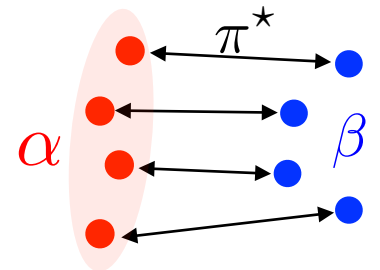


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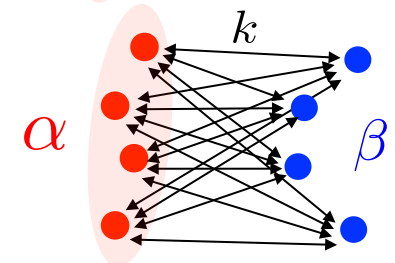
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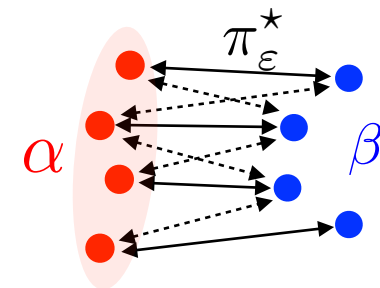
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Theorem: [Genevay, P, C, 17] $\bar{W}_{\varepsilon, p}^p(\alpha, \beta) \xrightarrow{\varepsilon \rightarrow 0} W_p^p(\alpha, \beta)$
 $\xrightarrow{\varepsilon \rightarrow +\infty} \|\alpha - \beta\|_k^2$

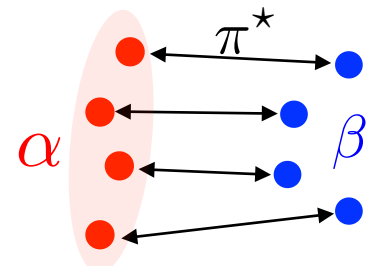
for $k(x, y) = -d(x, y)^p$

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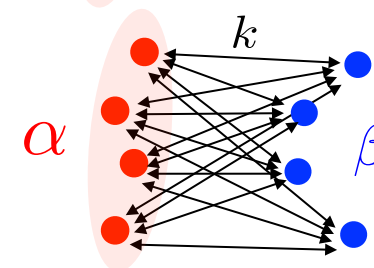
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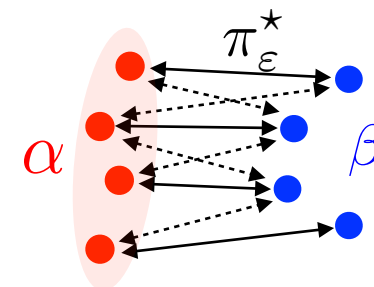
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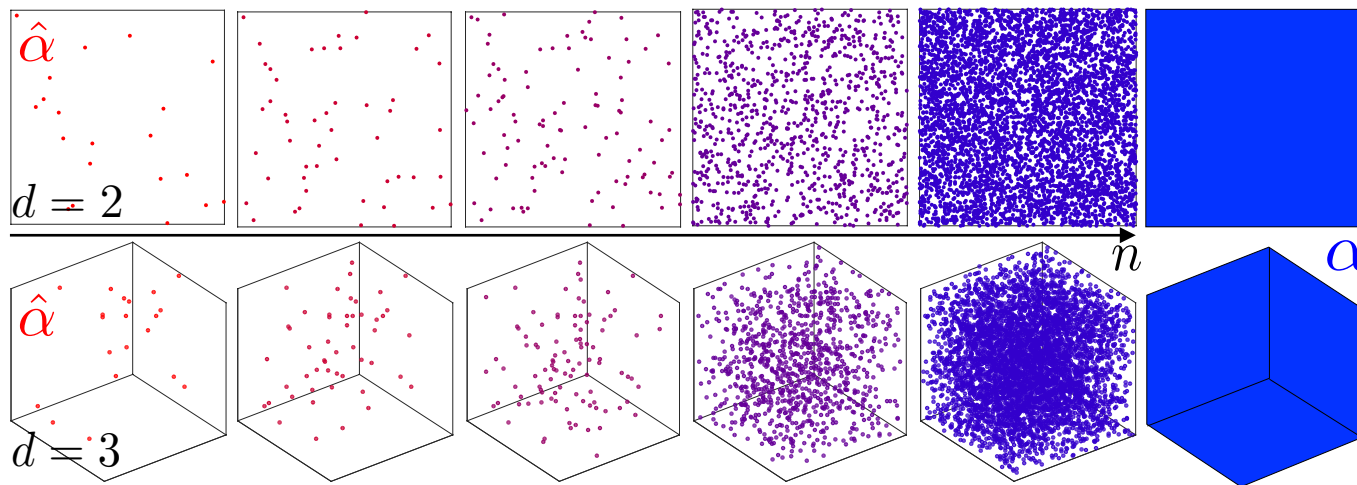
for $k(x, y) = -d(x, y)^p$

Best of both worlds:

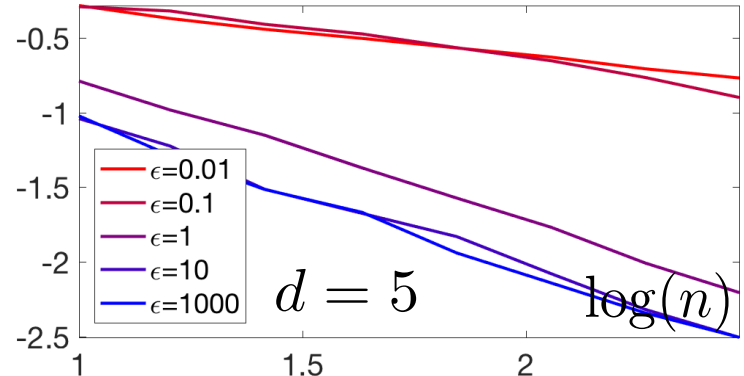
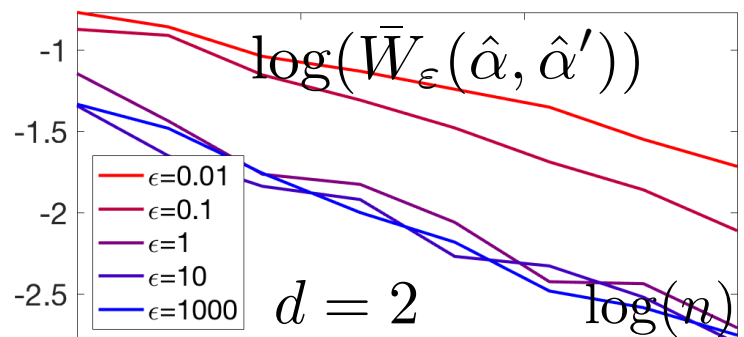
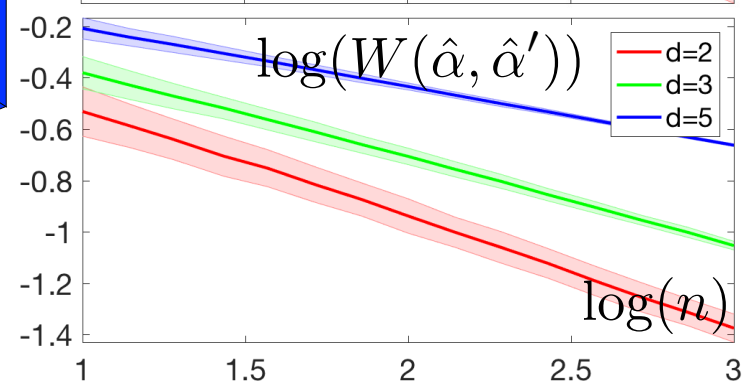
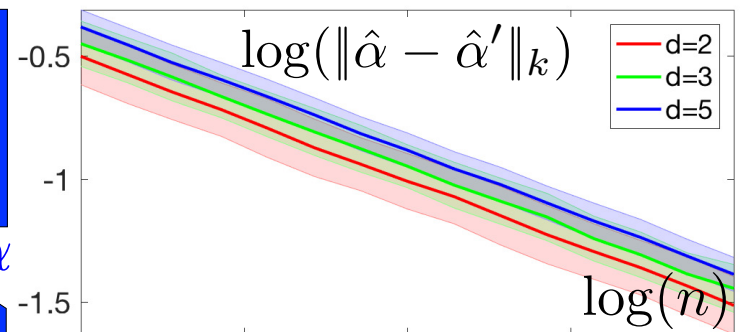
→ cross-validate ε

- Scale free (no σ , no heavy tail kernel).
- Non-Euclidean, arbitrary ground distance.
- Less biased gradient.
- No curse of dimension (low sample complexity).

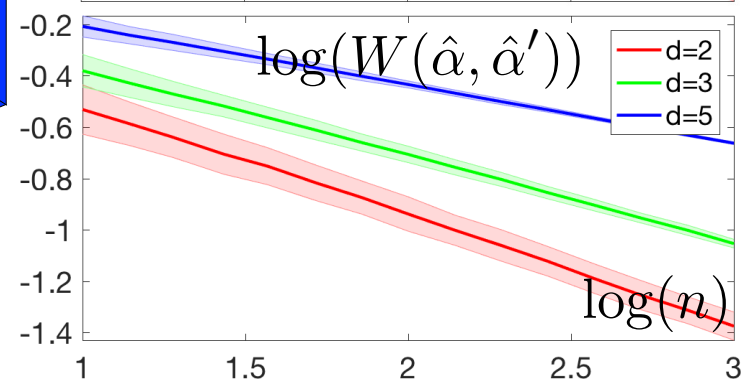
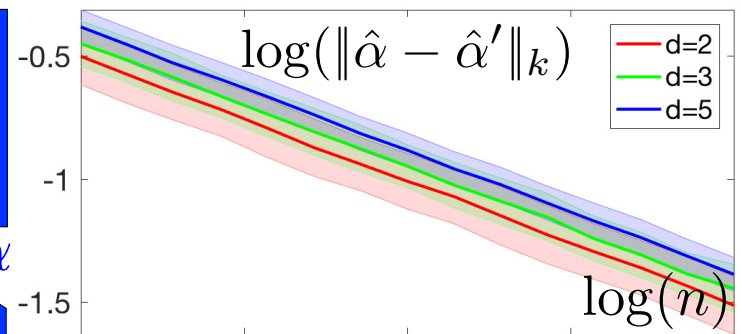
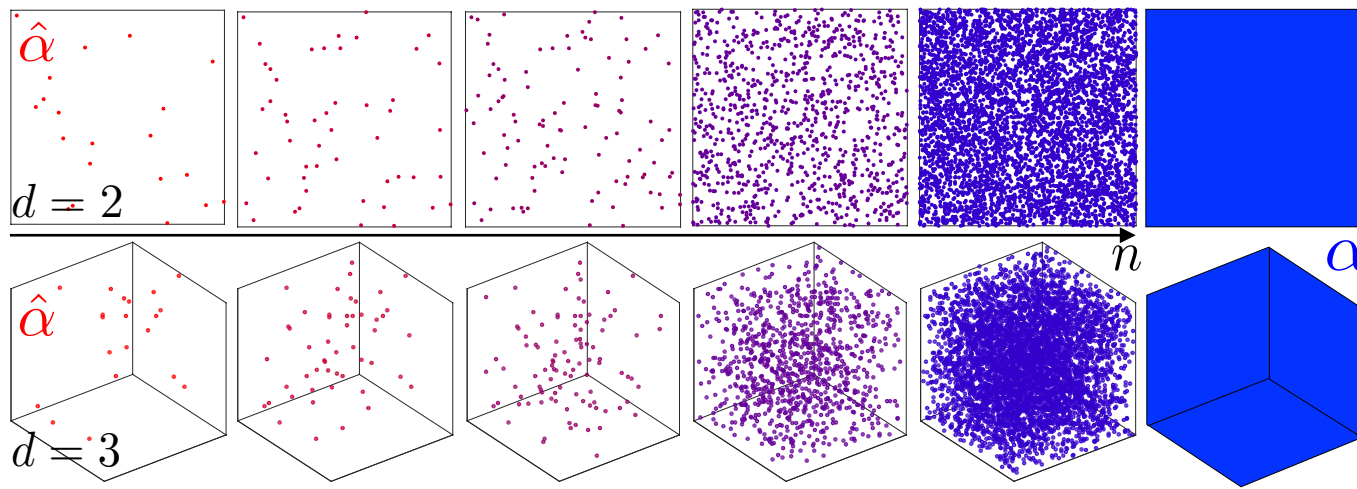
Sample Complexity



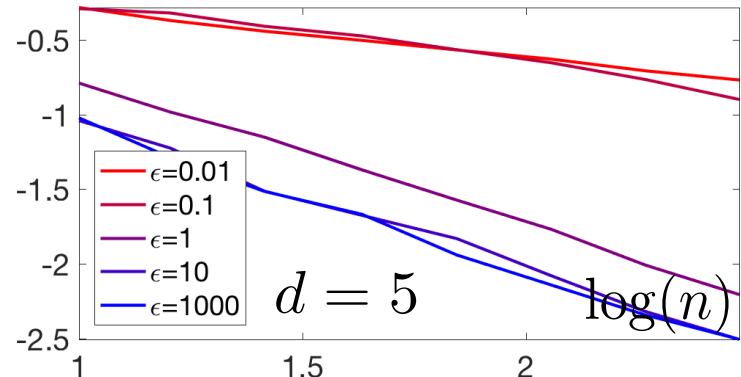
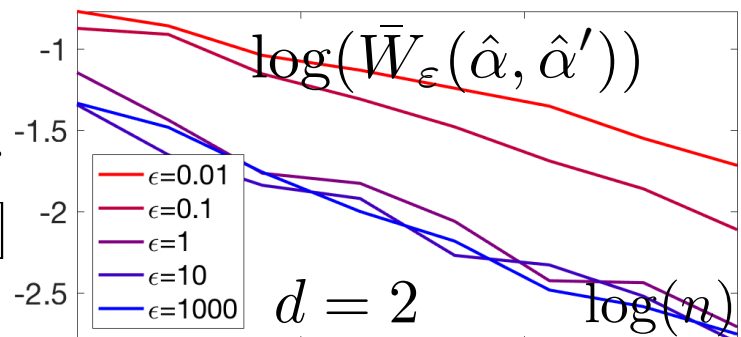
Theorem: $\mathbb{E}(|W(\hat{\alpha}, \hat{\beta}) - W(\alpha, \beta)|) = O(n^{-\frac{1}{d}})$
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Sample Complexity



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Optimal transport: suffers from curse of dimensionality.
 → Adapt to support dimensionality [Weed, Bach 2017]

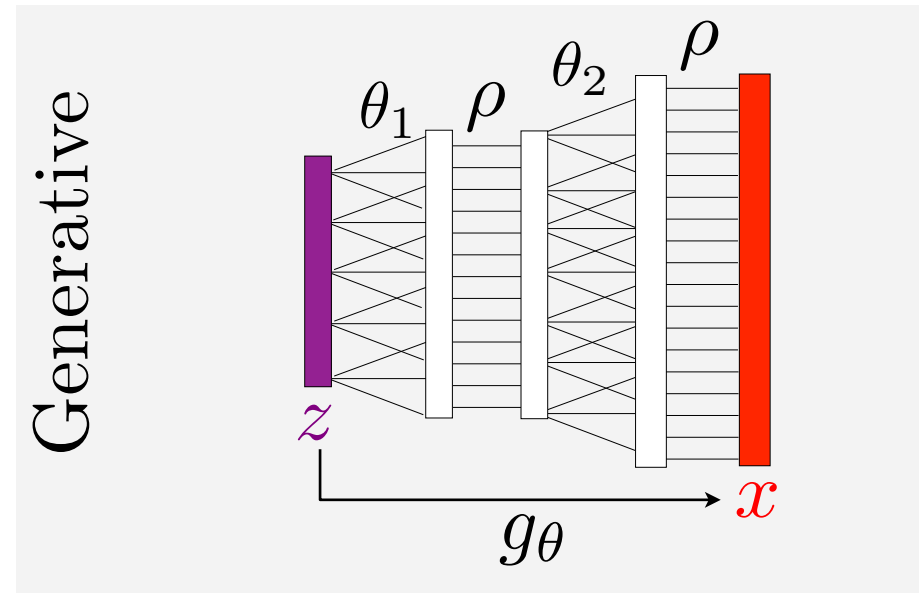
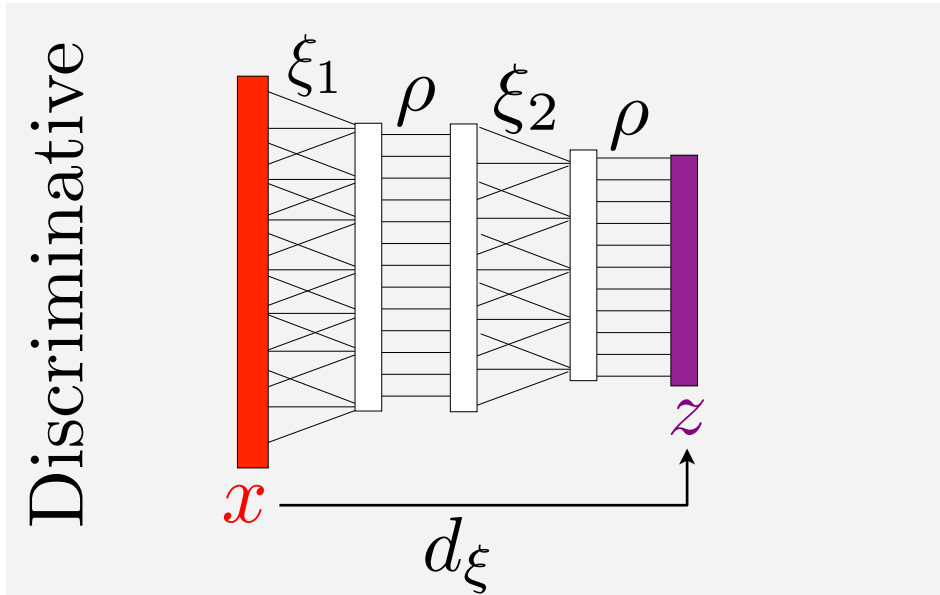
Open problem: sample complexity of \bar{W}_ϵ ?

Overview

- Csiszar Divergences
- Dual Norms and MMD
- Minimum Kantorovitch Estimators
- **Deep Generative Models Fitting**

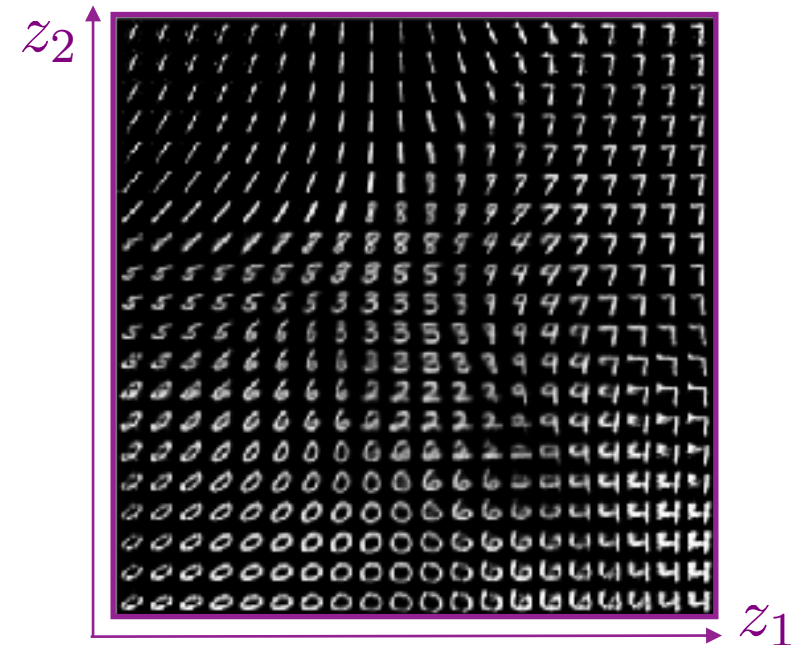
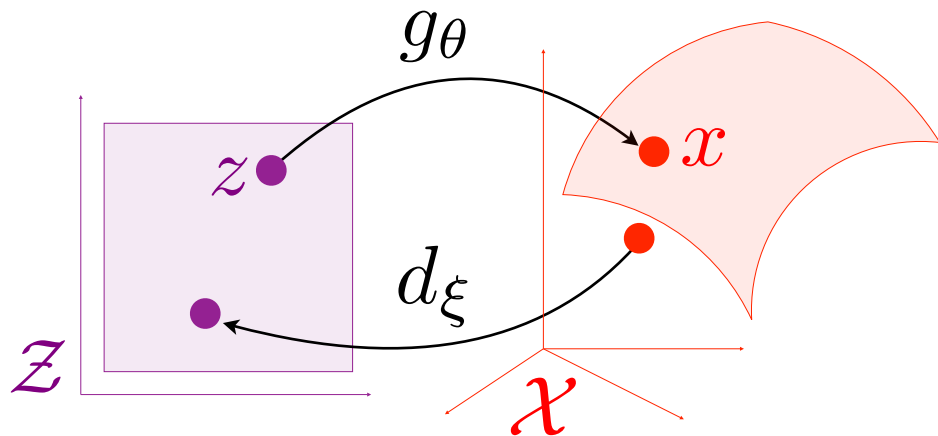
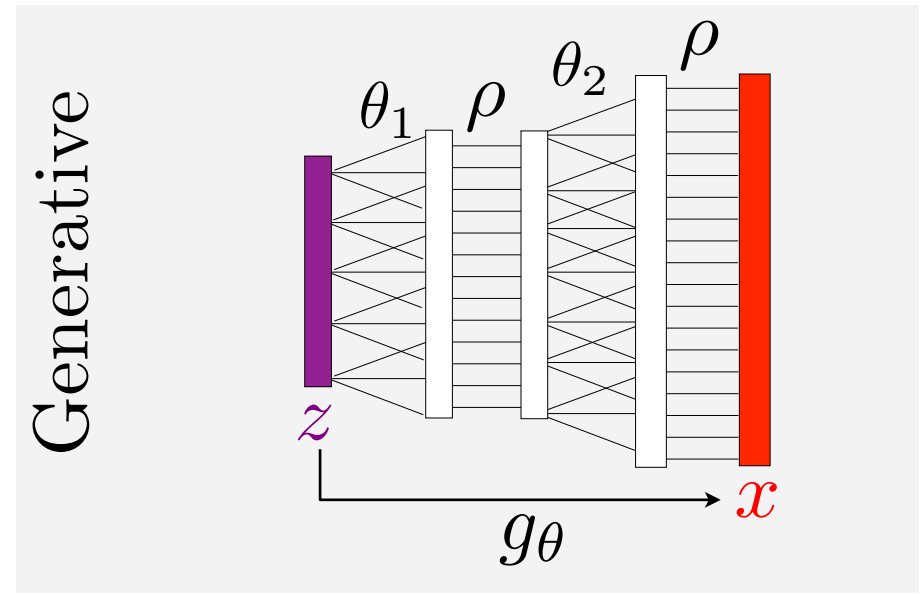
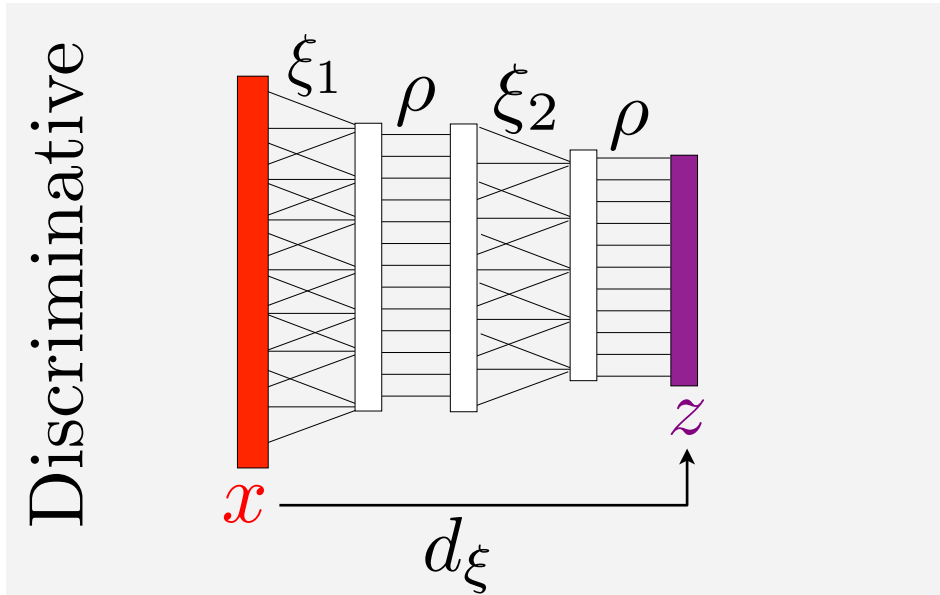
Deep Discriminative vs Generative Models

Deep networks: $d_{\xi}(x) = \rho(\xi_K(\dots \rho(\xi_2(\rho(\xi_1(x)\dots))$
 $g_{\theta}(z) = \rho(\theta_K(\dots \rho(\theta_2(\rho(\theta_1(z)\dots))$

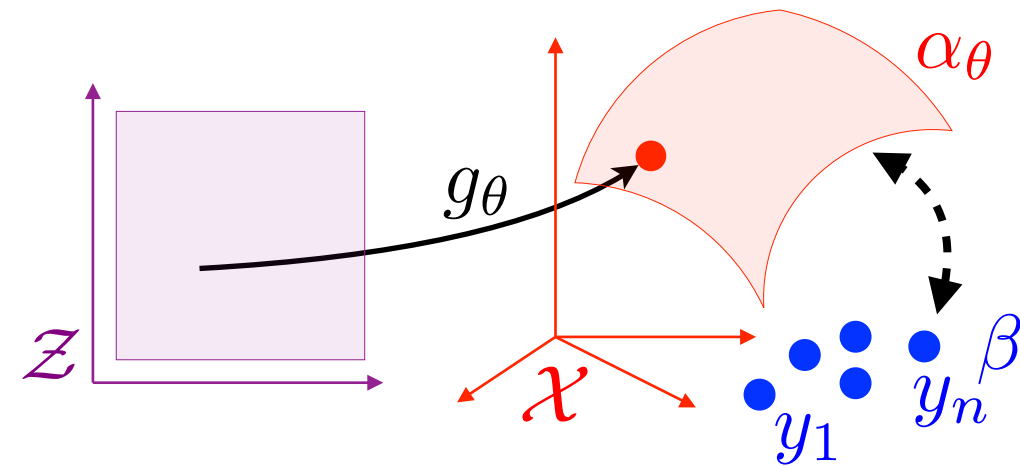


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Training Architecture



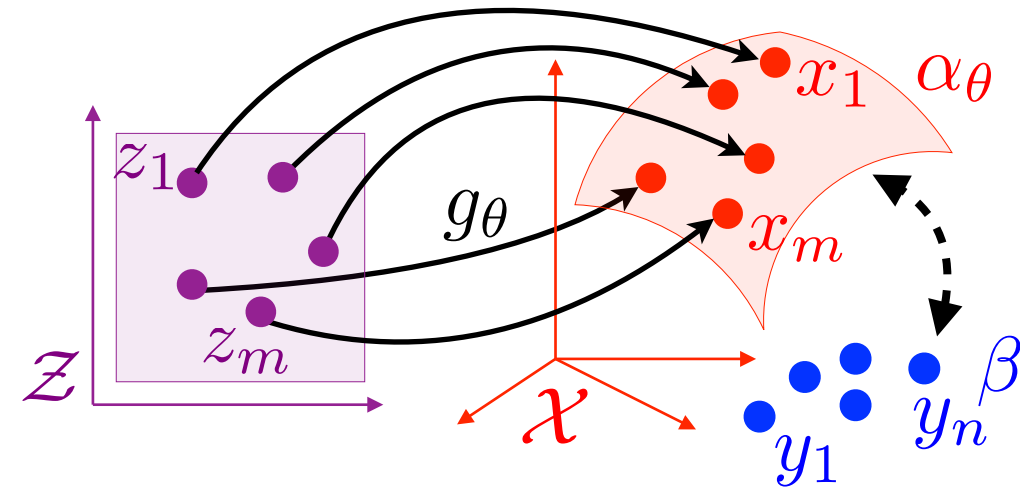
$$\min_{\theta} E(\theta) \stackrel{\text{def.}}{=} \bar{W}_\varepsilon(\alpha_\theta, \beta)$$

Stochastic gradient descent

$$\theta^{(\ell)} = \theta^{(\ell)} - \tau_\ell \nabla \hat{E}_L(\theta)$$

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Training Architecture



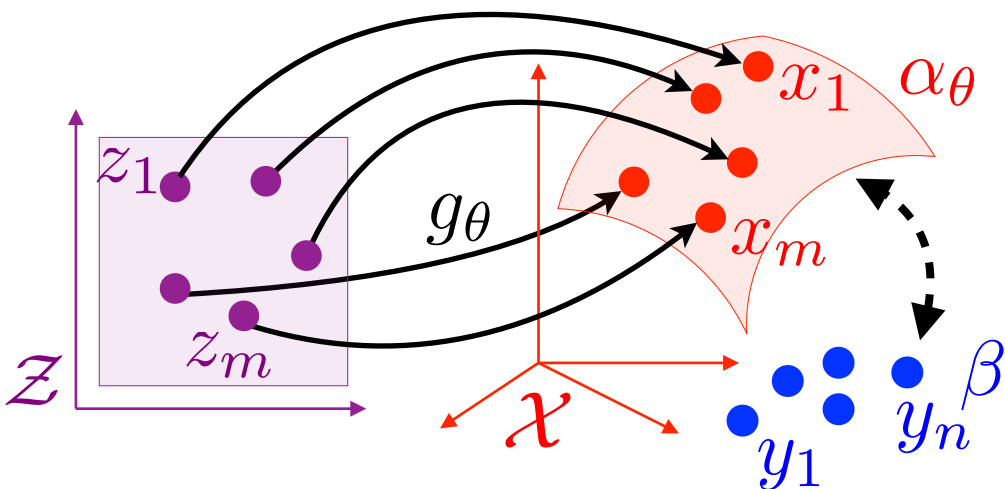
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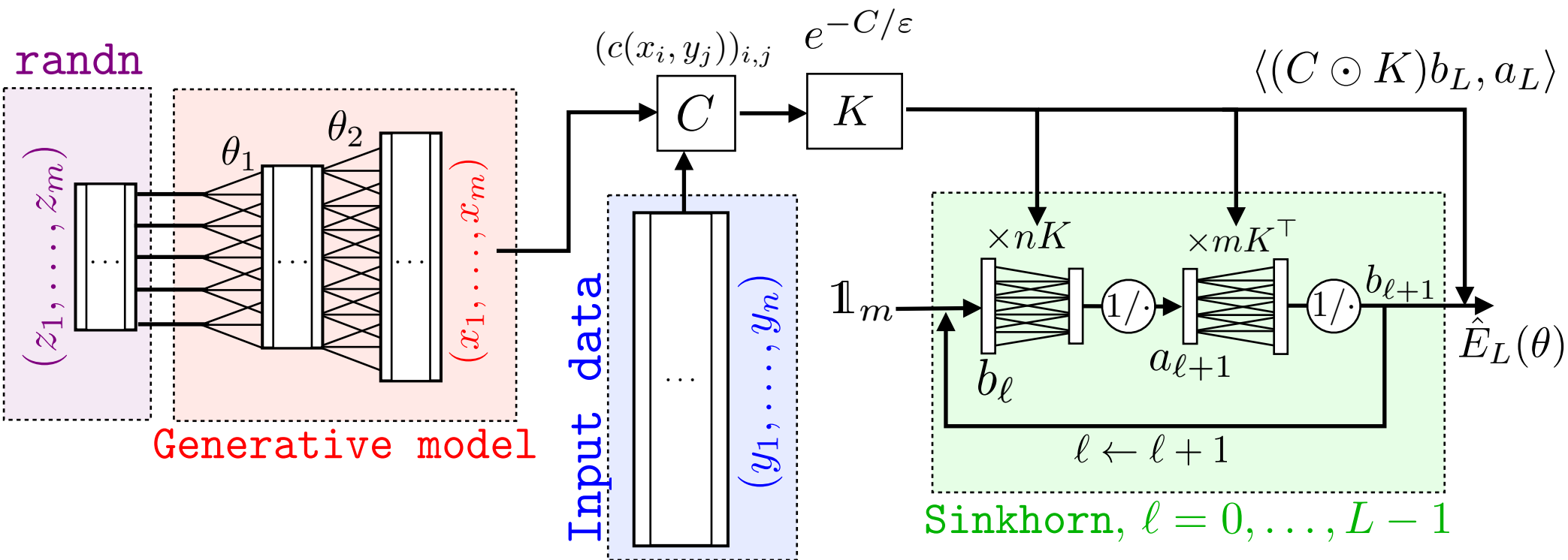


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Automatic Differentiation

Setup: $\mathcal{E} : \mathbb{R}^n \rightarrow \mathbb{R}$ computable in K operations.

```
def ForwardNN(A,b,Z):  
    X = []  
    X.append(Z)  
    for r in arange(0,R):  
        X.append( rhoF( A[r].dot(X[r]) + tile(b[r],[1,Z.shape[1]]) ) )  
    return X
```

Hypothesis: elementary operations ($a \times b$, $\log(a)$, \sqrt{a} ...) and their derivatives cost $O(1)$.

Question: What is the complexity of computing $\nabla \mathcal{E} : \mathbb{R}^n \rightarrow \mathbb{R}^n$?

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Finite differences:
$$\nabla \mathcal{E}(\theta) \approx \frac{1}{\varepsilon} (\mathcal{E}(\theta + \varepsilon \delta_1) - \mathcal{E}(\theta), \dots, \mathcal{E}(\theta + \varepsilon \delta_n) - \mathcal{E}(\theta))$$
$$K(n + 1) \text{ operations, intractable for large } n.$$

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 $K(n+1)$ operations, intractable for large n .

Theorem: there is an algorithm to compute $\nabla \mathcal{E}$ in $O(K)$ operations.
[Seppo Linnainmaa, 1970]

This algorithm is reverse mode automatic differentiation

```
def BackwardNE(A,b,X):  
    gx = lossG(X[R],Y) # initialize the gradient  
    for r in arange(R-1,-1,-1):  
        M = rhoG( A[r].dot(X[r]) + tile(b[r],[1,n]) ) * gx  
        gx = A[r].transpose().dot(M)  
        gA[r] = M.dot(X[r].transpose())  
        gb[r] = MakeCol(M.sum(axis=1))  
    return [gA,gb]
```



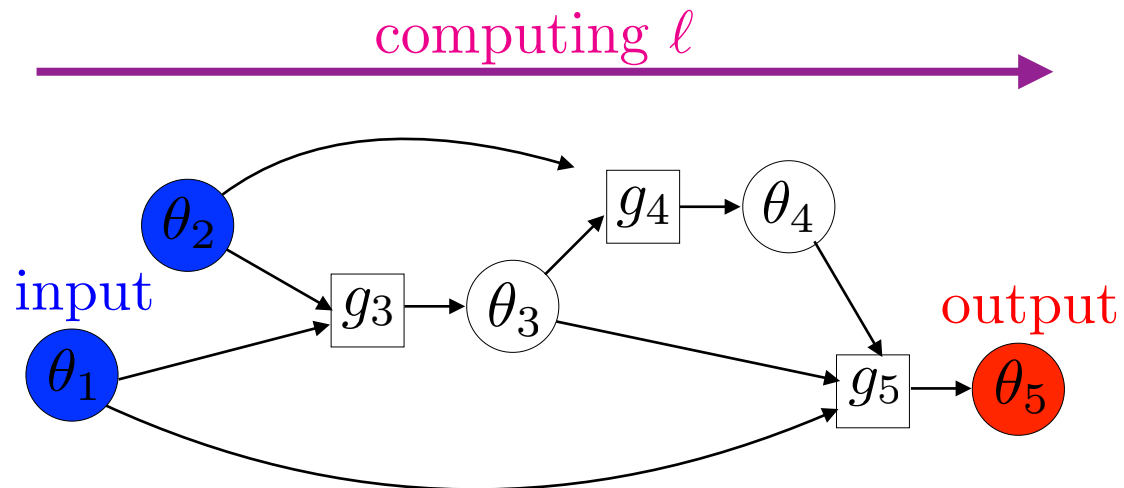
Computational Graph

Computational Graph

Computer program \Leftrightarrow directed acyclic graph \Leftrightarrow linear ordering of nodes $(\theta_r)_r$

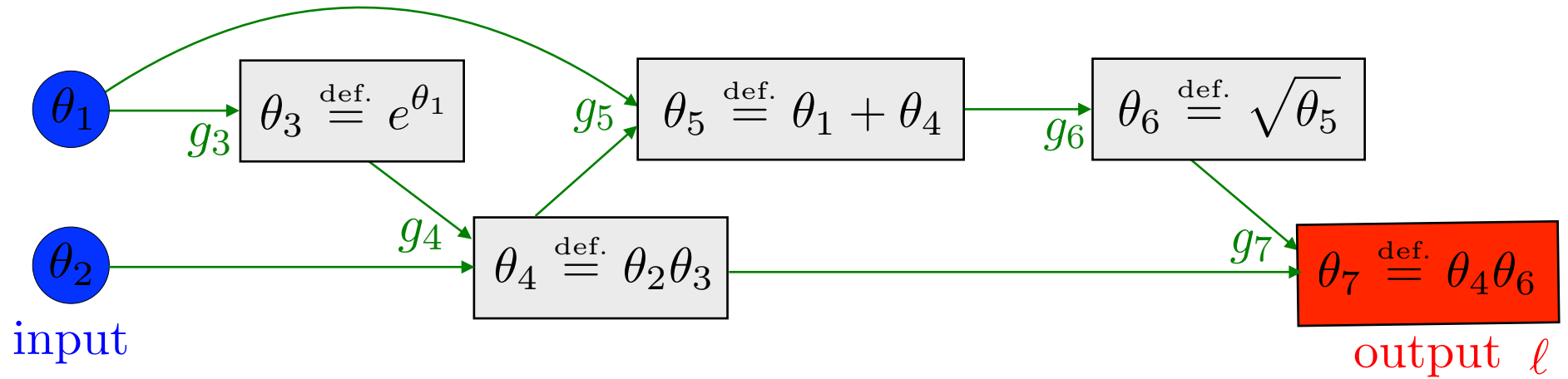
forward

```
function  $\ell(\theta_1, \dots, \theta_M)$ 
  for  $r = M + 1, \dots, R$ 
    |  $\theta_r = g_r(\theta_{\text{Parents}(r)})$ 
  return  $\theta_R$ 
```



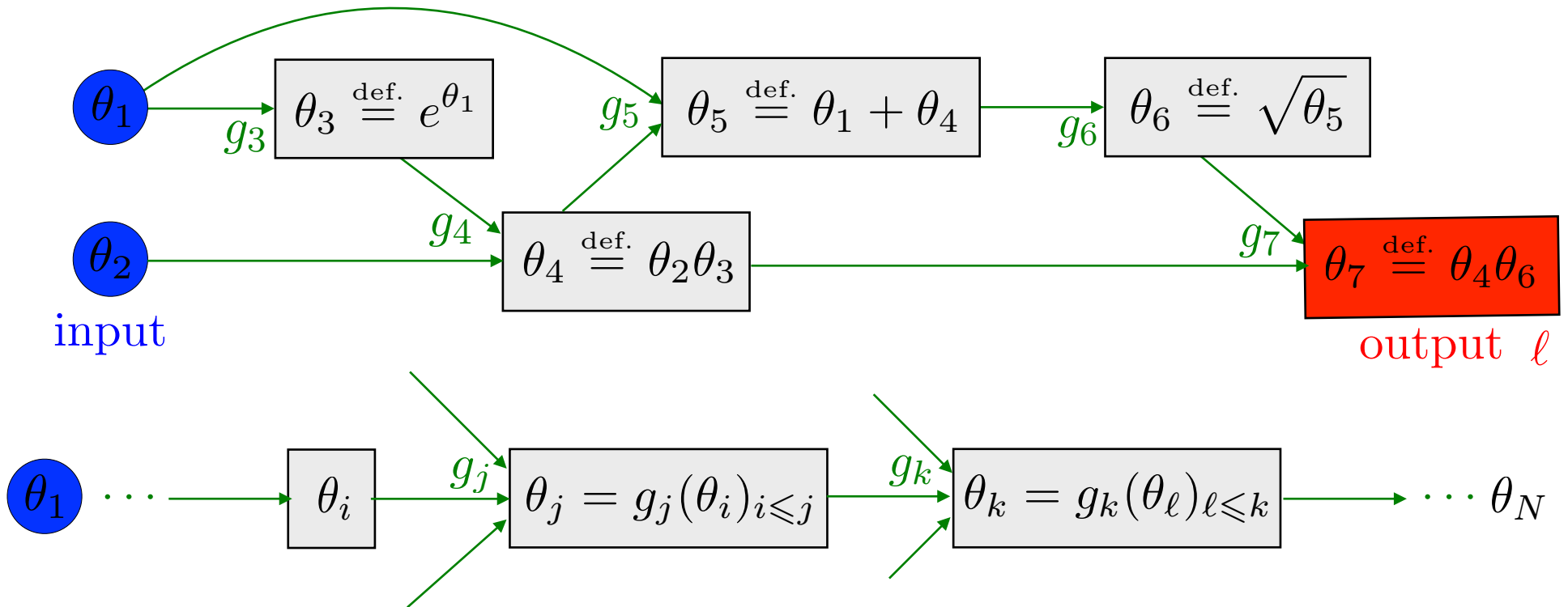
Example

$$l(\theta_1, \theta_2) \stackrel{\text{def.}}{=} \theta_2 e^{\theta_1} \sqrt{\theta_1 + \theta_2 e^{\theta_1}}$$



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$$l(\theta_1, \theta_2) \stackrel{\text{def.}}{=} \theta_2 e^{\theta_1} \sqrt{\theta_1 + \theta_2 e^{\theta_1}}$$



Chain rules:

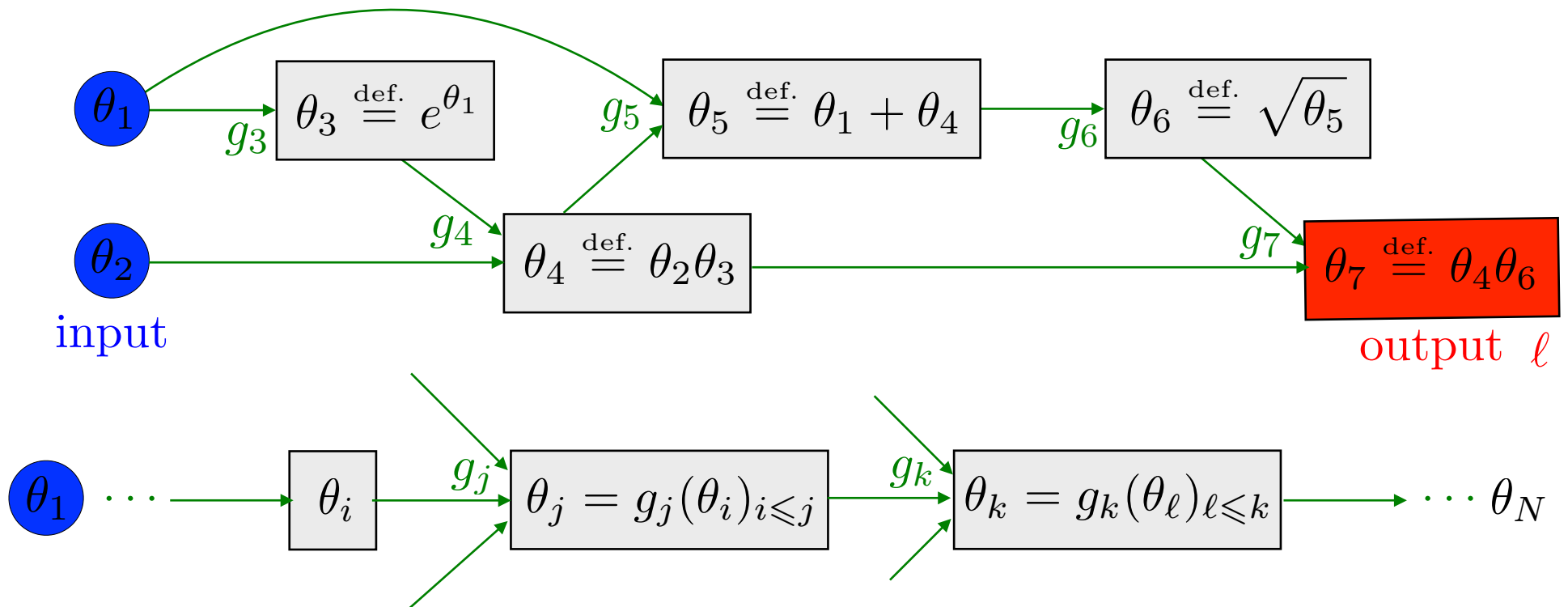
$$\left\langle \frac{\partial \theta_j}{\partial \theta_1} = \sum_{i \in \text{Parent}(j)} \frac{\partial \theta_j}{\partial \theta_i} \frac{\partial \theta_i}{\partial \theta_1} \right\rangle$$

\searrow
 $\partial_i g_j(\theta)$

“Classical” evaluation: **forward**.
Complexity \sim #inputs.

Example

$$l(\theta_1, \theta_2) \stackrel{\text{def.}}{=} \theta_2 e^{\theta_1} \sqrt{\theta_1 + \theta_2 e^{\theta_1}}$$



Chain rules:

$$\text{“} \frac{\partial \theta_j}{\partial \theta_1} = \sum_{i \in \text{Parent}(j)} \frac{\partial \theta_j}{\partial \theta_i} \frac{\partial \theta_i}{\partial \theta_1} \text{”}$$

$\searrow \quad \swarrow$
 $\partial_i g_j(\theta)$

“Classical” evaluation: **forward**.
Complexity \sim #inputs.

$$\text{“} \frac{\partial \theta_N}{\partial \theta_j} = \sum_{k \in \text{Child}(j)} \frac{\partial \theta_N}{\partial \theta_k} \frac{\partial \theta_k}{\partial \theta_j} \text{”}$$

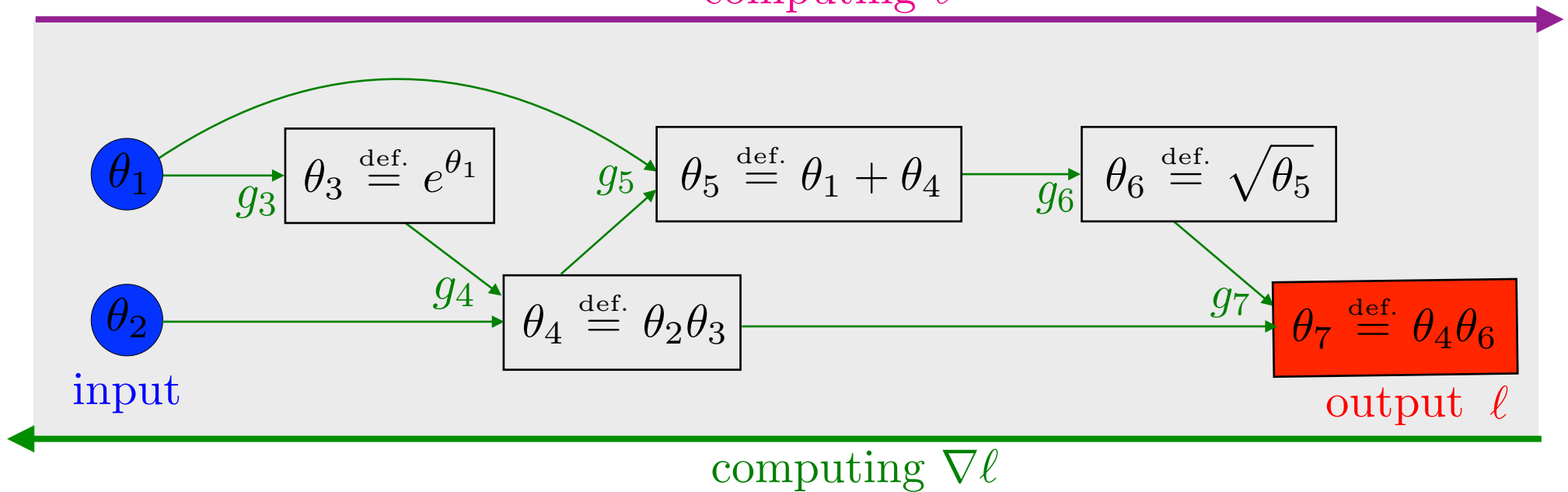
$\swarrow \quad \searrow$
 $\nabla_j l(\theta) \quad \nabla_k l(\theta) \quad \partial_j g_k(\theta)$

Backward evaluation.
Complexity \sim #outputs (1 for grad).

Backward Automatic Differentiation

$$l(\theta_1, \theta_2) \stackrel{\text{def.}}{=} \theta_2 e^{\theta_1} \sqrt{\theta_1 + \theta_2 e^{\theta_1}}$$

computing l



forward

```
function  $l(\theta_1, \dots, \theta_M)$ 
  for  $r = M + 1, \dots, R$ 
    |  $\theta_r = g_r(\theta_{\text{Parents}(r)})$ 
  return  $\theta_R$ 
```

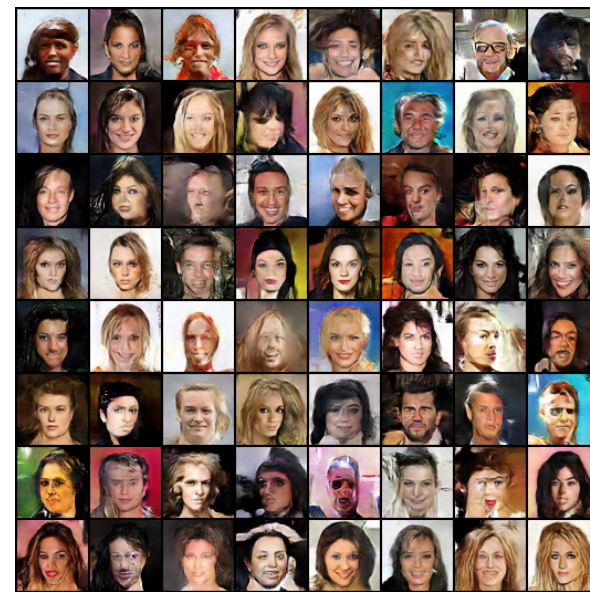
backward

```
function  $\nabla l(\theta_1, \dots, \theta_M)$ 
   $\nabla_R l = 1$ 
  for  $r = R - 1, \dots, 1$ 
    |  $\nabla_r l = \sum_{s \in \text{Child}(r)} \partial_r g_s(\theta) \nabla_s l$ 
  return  $(\nabla_1 l, \dots, \nabla_M l)$ 
```

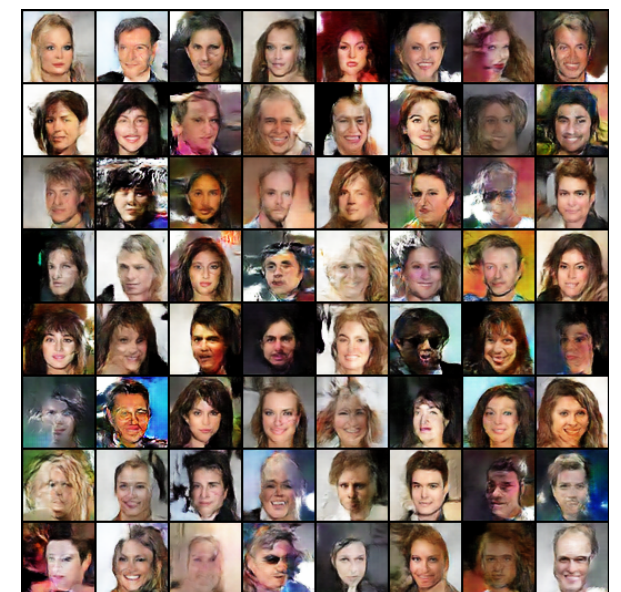
Examples of Image Generation



Inputs



Small ϵ



Large ϵ

- Need to learn the metric $c(x, y) = \|d_\xi(x) - d_\xi(y)\|^p$ (\sim GANs)
- Performance evaluation of generative models is an open problem.



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